On smooth change-point location estimation for Poisson processes and Skorokhod topologies

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30 years of LMM

Le Mans — May 21, 2024



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- 3 Regular model
- 4 Change-point model
- 5 Smooth change-point model
- 6 Skorokhod topologies and Ibragimov-Khasminskii method

7 Some tools for studying the convergence in the topology  $M_1$ 

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- 7) Some tools for studying the convergence in the topology  $M_1$

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**Recalls:**  $X = (X(t), 0 \le t \le T)$  is an (inhomogeneous) Poisson process of intensity function  $\lambda(\cdot)$  if X(0) = 0 and the increments of X on disjoint intervals are independent Poisson random variables:

$$\mathbf{P}\{X(t) - X(s) = k\} = \frac{\left(\int_{s}^{t} \lambda(t) \, \mathrm{d}t\right)^{k}}{k!} \exp\left\{-\int_{s}^{t} \lambda(t) \, \mathrm{d}t\right\}.$$

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The process  $X = (X(t), 0 \le t \le T)$  is a counting process. The (random) set  $\{t_1, t_2, \dots, t_{X(T)}\}$  of its jump times is a point process.

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The stochastic integral with respect to X is

$$\int_0^T f(t) \, \mathrm{d}X(t) = \sum_{i=1}^{X(T)} f(t_i).$$

**Observation:**  $X^{(n)} = (X_1, \ldots, X_n)$ , where  $X_j = (X_j(t), 0 \le t \le \tau)$ ,  $j = 1, \ldots, n$ , are independent Poisson processes of intensity function  $\lambda_{\theta}(\cdot)$  with some unknown parameter  $\theta$ .

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Aim: estimate  $\theta$  as  $n \to +\infty$ .



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On smooth change-point estimation and Skorokhod topologies





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$$\lambda_{\theta}^{(n)}(t) = \mathbf{a} + \frac{\mathbf{r}}{\delta_n} (t - \theta) \mathbb{1}_{[\theta, \theta + \delta_n)}(t) + \mathbf{r} \mathbb{1}_{[\theta + \delta_n, \tau]}(t), \quad 0 \le t \le \tau,$$

with  $\delta_n \searrow 0$  and unknown parameter  $\theta \in (\alpha, \beta) \subset (0, \tau)$ .

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The likelihood (with respect to *n* independent homogeneous Poisson processes of unit intensity) is

$$\mathbf{L}(\theta, X^{(n)}) = \exp\left\{\sum_{j=1}^n \int_0^\tau \ln \lambda_{\theta}^{(n)}(t) \, \mathrm{d}X_j(t) - n \int_0^\tau \left(\lambda_{\theta}^{(n)}(t) - 1\right) \, \mathrm{d}t\right\}$$

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The Bayes estimator (BE)  $\tilde{\theta}_n$  for quadratic loss and prior density  $p(\cdot)$  (supposed continuous and strictly positive) is

$$\widetilde{\theta}_n = \frac{\int_{\alpha}^{\beta} \theta \, p(\theta) \, \mathsf{L}(\theta, X^{(n)}) \, \mathrm{d}\theta}{\int_{\alpha}^{\beta} p(\theta) \, \mathsf{L}(\theta, X^{(n)}) \, \mathrm{d}\theta}$$

## First find a normalization rate $\varphi_n \searrow 0$

$$Z_n(u) = rac{\mathsf{L}ig( heta + u\,arphi_n, X^{(n)}ig)}{\mathsf{L}ig( heta, X^{(n)}ig)}, \quad u \in \mathbb{R},$$

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Then deduce that:

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• the MLE and the BEs are consistent;

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Then deduce that:

- the MLE and the BEs are consistent;
- they converge at rate  $\varphi_n$ , more precisely,  $\varphi_n^{-1}(\widehat{\theta}_n \theta) \Rightarrow \xi$ and  $\varphi_n^{-1}(\widetilde{\theta}_n - \theta) \Rightarrow \zeta$  with

$$\xi = \underset{u \in \mathbb{R}}{\operatorname{argsup}} Z(u) \quad \text{and} \quad \zeta = \frac{\int_{\mathbb{R}} u Z(u) \, \mathrm{d} u}{\int_{\mathbb{R}} Z(u) \, \mathrm{d} u};$$
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in particular,  $\varphi_n^{-2} \mathbf{E} |\widehat{\theta}_n - \theta|^2 \to \mathbf{E} \xi^2$  and  $\varphi_n^{-2} \mathbf{E} |\widetilde{\theta}_n - \theta|^2 \to \mathbf{E} \zeta^2;$ 

$$Z_n(u) = \frac{\mathsf{L}\big(\theta + u\,\varphi_n, X^{(n)}\big)}{\mathsf{L}\big(\theta, X^{(n)}\big)}, \quad u \in \mathbb{R},$$

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• in particular,  $\varphi_n^{-2} \mathbf{E} |\widehat{\theta}_n - \theta|^2 \to \mathbf{E} \xi^2$  and  $\varphi_n^{-2} \mathbf{E} |\widetilde{\theta}_n - \theta|^2 \to \mathbf{E} \zeta^2$ ; • the BEs are asymptotically efficient.

$$Z_n(u) = \frac{\mathsf{L}\big(\theta + u\,\varphi_n, X^{(n)}\big)}{\mathsf{L}\big(\theta, X^{(n)}\big)}, \quad u \in \mathbb{R},$$

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 $\mathbf{E} \zeta^2$  is an asymptotic lower bound on MSEs of all estimators.

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 When the trajectories of these processes are continuous, the weak convergence takes place in the space C<sub>0</sub>(ℝ) of continuous functions on ℝ vanishing at ±∞ equipped with the sup norm. Two functional spaces were used for the convergence of  $Z_n(\cdot)$  to  $Z(\cdot)$  in the Ibragimov-Khasminskii method:

- When the trajectories of these processes are continuous, the weak convergence takes place in the space  $\mathscr{C}_0(\mathbb{R})$  of continuous functions on  $\mathbb{R}$  vanishing at  $\pm \infty$  equipped with the sup norm.
- When the trajectories of these processes are discontinuous, the weak convergence takes place in the space D<sub>0</sub>(ℝ) of càdlàg functions on ℝ vanishing at ±∞ equipped with the "usual" Skorokhod topology.



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Regular model	Properties of the estimators
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$$I_n(\theta) = n \int_0^T \frac{\left(\dot{\lambda}_{\theta}(t)\right)^2}{\lambda_{\theta}(t)} dt = n \frac{r}{\delta} \ln\left(\frac{a+r}{a}\right) = n I,$$

and the properties of the MLE and of the BEs are given by:

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and the properties of the MLE and of the BEs are given by:

## Theorem

- The MLE and the BEs are consistent.
- They are asymptotically normal (with classic rate  $\frac{1}{\sqrt{n}}$ ):

$$\sqrt{n}(\widehat{\theta}_n - \theta) \Rightarrow \mathcal{N}\left(0, \frac{1}{I}\right) \quad \text{and} \quad \sqrt{n}\left(\widetilde{\theta}_n - \theta\right) \Rightarrow \mathcal{N}\left(0, \frac{1}{I}\right).$$

- The convergence of moments in these convergences in law holds.
- Both the MLE and the BEs are asymptotically efficient.

Regular model	Weak convergence behind
---------------	-------------------------

Choosing 
$$\varphi_n = \frac{1}{\sqrt{n}}$$
 and denoting  
$$Z_I(u) = \exp\left\{u\,\Delta - \frac{u^2}{2}\,I\right\}, \quad u \in \mathbb{R},$$

where  $\Delta \subseteq \mathcal{N}(0, I)$ , we have the weak convergence in the space  $\mathscr{C}_0(\mathbb{R})$  of the normalized likelihood ratio  $Z_n(\cdot)$  to the limit likelihood ratio  $Z_l(\cdot)$ .

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Further, we have

and

$$\xi = \underset{u \in \mathbb{R}}{\operatorname{argsup}} Z_{I}(u) = \frac{\Delta}{I} \quad \text{and} \quad \zeta = \frac{\int_{\mathbb{R}} u Z(u) \, \mathrm{d}u}{\int_{\mathbb{R}} Z(u) \, \mathrm{d}u} = \frac{\Delta}{I},$$
  
so  $\xi = \zeta \subseteq \mathcal{N}\left(0, \frac{1}{I}\right).$ 



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On smooth change-point estimation and Skorokhod topologies

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$$Z_{a,a+r}(u) = \begin{cases} \exp\left\{\ln\left(\frac{a}{a+r}\right)Y_{a+r}(u) + r u\right\}, & \text{if } u \ge 0, \\ \exp\left\{\ln\left(\frac{a+r}{a}\right)Y_{a}(-u) + r u\right\}, & \text{if } u \le 0, \end{cases}$$

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$$n(\widehat{\theta}_n - \theta) \Rightarrow \xi_{a,a+r}$$
 and  $n(\widetilde{\theta}_n - \theta) \Rightarrow \zeta_{a,a+r}$ .

- The convergence of moments in these convergences in law holds.
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Choosing  $\varphi_n = \frac{1}{n}$ , we have the weak convergence in the space  $\mathscr{D}_0(\mathbb{R})$  of the normalized likelihood ratio  $Z_n(\cdot)$  to the limit likelihood ratio  $Z_{a,a+r}(\cdot)$ .



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So, is our model regular with rate  $\sqrt{\frac{\delta_n}{n}} \ll \frac{1}{\sqrt{n}}$ ?

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Certainly not for all choices of  $\delta_n!$  If, for example,  $\delta_n \ll \frac{1}{r}$ , we would have  $\sqrt{\frac{\delta_n}{n}} \ll \frac{1}{n}$ , which should not be possible.

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In fact, the behavior of the estimators is essentially different in the following two cases:

• 
$$n \delta_n \rightarrow +\infty$$
 (slow case),

• 
$$n \delta_n \rightarrow 0$$
 (fast case).

## Theorem

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• The MLE and the BEs are consistent.

• They are asymptotically normal with rate  $\sqrt{\frac{\delta_n}{n}}$ :

$$\sqrt{\frac{n}{\delta_n}}(\widehat{\theta}_n - \theta) \Rightarrow \mathcal{N}\left(0, \frac{1}{F}\right) \text{ and } \sqrt{\frac{n}{\delta_n}}(\widetilde{\theta}_n - \theta) \Rightarrow \mathcal{N}\left(0, \frac{1}{F}\right).$$

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## The model is still regular (LAN).

The model is still regular (LAN): choosing  $\varphi_n = \sqrt{\frac{\delta_n}{n}}$  and denoting, as before,

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where  $\Delta \subseteq \mathcal{N}(0, F)$ , we have the weak convergence in the space  $\mathscr{C}_0(\mathbb{R})$  of the normalized likelihood ratio  $Z_n(\cdot)$  to the limit likelihood ratio  $Z_F(\cdot)$ .

#### Recall:

$$Z_{a,a+r}(u) = \begin{cases} \exp\left\{\ln\left(\frac{a}{a+r}\right)Y_{a+r}(u) + r u\right\}, & \text{if } u \ge 0, \\ \exp\left\{\ln\left(\frac{a+r}{a}\right)Y_{a}(-u) + r u\right\}, & \text{if } u \le 0, \end{cases}$$

$$\xi_{a,a+r} = \operatorname*{argsup}_{u \in \mathbb{R}} Z_{a,a+r}(u),$$

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Suppose  $n \delta_n \rightarrow 0$ . Then:

- The MLE and the BEs are consistent.
- They converge at rate  $\frac{1}{n}$ :  $n(\widehat{\theta}_n - \theta) \Rightarrow \xi_{a,a+r}$  and  $n(\widetilde{\theta}_n - \theta) \Rightarrow \zeta_{a,a+r}$ .
- The convergence of moments in these convergences in law holds.
- The BEs are asymptotically efficient.

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However, the trajectories of  $Z_n(\cdot)$  are continuous, while those of  $Z_{a,a+r}(\cdot)$  are discontinuous, and so  $Z_n(\cdot)$  cannot converge to  $Z_{a,a+r}(\cdot)$  in the space  $\mathcal{D}_0(\mathbb{R})$  equipped with the "usual" Skorokhod topology.



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# 6 Skorokhod topologies and Ibragimov-Khasminskii method

### 7) Some tools for studying the convergence in the topology $M_{ m 1}$

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Four topologies introduced by Skorokhod (1956):

$$U \Rightarrow J_1 \overset{\nearrow}{\underset{\cong}{\boxtimes}} \frac{J_2}{M_1 \overset{\otimes}{\nearrow}} M_2.$$

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The "usual" Skorokhod topology  $J_1$ : on  $\mathscr{D}_0(\mathbb{R})$  it is defined by the distance

$$d^{(J_1)}(f,g) = \inf_{\nu} \left[ \sup_{u \in \mathbb{R}} \left| f(u) - g(\nu(u)) \right| + \sup_{u \in \mathbb{R}} \left| u - \nu(u) \right| \right],$$

with inf taken over all continuous one-to-one mappings  $\nu : \mathbb{R} \to \mathbb{R}$ .

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The topology  $M_1$ : on  $\mathscr{D}_0(\mathbb{R})$  it is defined by the distance  $d^{(M_1)}(f,g) = \inf \sup_{s \in \mathbb{R}} d\Big( (t_1(s), y_1(s)); (t_2(s), y_2(s)) \Big),$ 

with inf taken over all parametric representations  $(t_1(\cdot), y_1(\cdot))$  and  $(t_2(\cdot), y_2(\cdot))$  of the graphs  $\Gamma_f$  and  $\Gamma_g$  of f and g.

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Modulus of continuity of the topology  $J_1$ :

$$\Delta_h^{(J_1)}(f) = \sup\min\{|f(u) - f(u')|, |f(u) - f(u'')|\} + \sup_{|u| > 1/h} |f(u)|$$

with sup taken over  $u, u', u'' \in \mathbb{R}$  :  $u - h \le u' \le u \le u'' \le u + h$ .

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with sup taken over  $u,u',u''\in \mathbb{R}$  :  $u-h\leq u'\leq u\leq u''\leq u+h.$ 

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Modulus of continuity restricted to an interval  $[A, B] \subset \mathbb{R}$ :

$$\Delta_h^{(M_1)}(f; [A, B]) = \sup_{u \in [A, B]} \sup_{u-h \le u' \le u \le u'' \le u+h} d(f(u); [f(u'), f(u'')]).$$

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Let the processes  $Y_n(\cdot)$  and  $Y(\cdot)$  with trajectories in  $\mathcal{D}_0(\mathbb{R})$ . Then  $Y_n(\cdot)$  converges weakly to  $Y(\cdot)$  in the topology  $M_1$  if and only if:

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- $\lim_{h\to 0} \lim_{n\to +\infty} \mathbf{P}(\Delta_h^{(M_1)}(Y_n) > \varepsilon) = 0$  for all  $\varepsilon > 0$  (tightness).

Suppose that:

 the finite dimensional distributions of the normalized likelihood ratio Z<sub>n</sub>(·) converge to those of some Z(·) having a unique argsup;

• 
$$\mathbf{E} |Z_n^{1/2}(u) - Z_n^{1/2}(v)|^2 \le C|u-v|;$$

• 
$$\mathsf{E} Z_n^{1/2}(u) \leq \exp \left\{ -g(|u|) \right\}$$
 with  $g(\ell) \geq \kappa \ell \ (\forall \ \ell \in \mathbb{N});$ 

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as well as

• 
$$\mathbf{P}\left(\Delta_h^{(M_1)}(Z_n^{1/2}; [\ell, \ell+1]) > h^{\gamma_1}\right) \le B(\ell) h^{\gamma_2} \ (\forall \ 0 < h < h_0),$$
  
with  $B(\cdot)$  of at most polynomial growth.

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with  $B(\cdot)$  of at most polynomial growth.

Then  $Z_n(\cdot)$  converges weakly to  $Z(\cdot)$  in the topology  $M_1$ , and the properties of the MLE follow.

For our model, in the fast case, we show that:  $\exists \gamma, h_0, C > 0$  such that  $\forall 0 < h < h_0$  it holds

$$\mathbf{P}\Big(\Delta_h^{(M_1)}\big(Z_n^{1/2};[\ell,\ell+1]\big)>h^{\gamma}\Big)\leq C\ h^{2\gamma}.$$

For our model, in the fast case, we show that:  $\exists \gamma, h_0, C > 0 \text{ such that } \forall 0 < h < h_0 \text{ it holds}$   $\mathbf{P} \Big( \Delta_h^{(M_1)} \big( Z_n^{1/2}; [\ell, \ell+1] \big) > h^\gamma \Big) \leq C h^{2\gamma}.$ 

This yields the weak convergence of  $Z_n(\cdot)$  to  $Z_{a,a+r}(\cdot)$  in the topology  $M_1$  and the properties of the MLE.



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7 Some tools for studying the convergence in the topology  $M_1$ 

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Recall:

• 
$$\Delta_h^{(M_1)}(f) = \sup_{u,u',u'' \in [a,b] : u-h \le u' \le u \le u'' \le u+h} d(f(u); [f(u'), f(u'')]),$$
  
•  $\Delta_h^{(U)}(f) = \sup_{u,v \in [a,b] : u \le v \le u+h} |f(v) - f(u)|.$ 

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•  $\Delta_h^{(U)}(f) = \sup_{\substack{u,v \in [a,b] : u \le v \le u+h}} |f(v) - f(u)|.$ 

Introduce:

- modulus of increase  $\Delta_h^+(f) = \sup_{u,v \in [a,b] : u \le v \le u+h} (f(v) f(u))_+$ ,
- modulus of decrease  $\Delta_h^-(f) = \sup_{u,v \in [a,b] : u \le v \le u+h} (f(v) f(u))_-$ .

Recall:

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4

**Corollary:** If f is a monotonic, then  $\Delta_h^{(M_1)}(f) = 0!$ 

**Proposition:** If the jumps of f have the same sign and are summable, then

$$\Delta_h^{(M_1)}(f) \leq \Delta_h^{(U)}(f_{ ext{c.}}),$$

where  $f_{c.}$  is the continuous part of f.

### Recall: *f* is *L*-Lipschitz if $\forall u, v \in [a, b]$

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- f is L-Lipschitz decreasing if  $\forall u, v \in [a, b]$  such that  $u \leq v$ ,

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### Proposition:

- f is L-Lipschitz increasing  $\iff \Delta_h^+(f) \leq Lh$ ,
- f is *L*-Lipschitz decreasing  $\iff \Delta_h^-(f) \leq Lh$ .

**Proposition:** Let f be continuous and piecewise differentiable. Then:

- f is L-Lipschitz increasing  $\iff f'(t) \le L$ ,
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Generalizes to càdlàg piecewise differentiable functions with the convention that the derivative is infinite at jump points:

$$f'(t) = egin{cases} +\infty, & ext{if } f(t)-f(t-)>0, \ -\infty, & ext{if } f(t)-f(t-)<0. \end{cases}$$

# Thank you for your attention!