

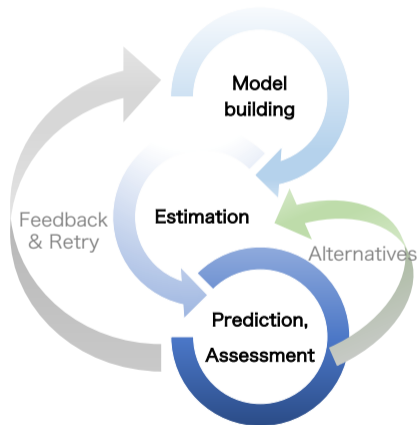
Gaussian quasi-likelihood inference for ergodic Lévy driven SDE

Hiroki Masuda

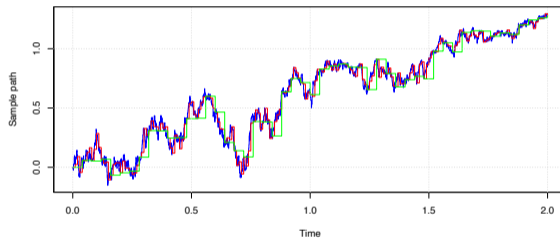
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EFFI Spring School, Le Mans
May 27 & 28, 2024

Inference for an ergodic Lévy driven stochastic differential equation (SDE)



$$X_{t+dt} \leftarrow X_t + (\text{Trend})dt + (\text{Scale}) \cdot d(\text{Noise})$$



Scale

Estimation · Selection

Trend (Drift)

Estimation · Selection

Noise
Structure

Contents

- 1 Setup and objective
- 2 Estimation: GQMLE
- 3 Selection: GQAIC and GQBIC
- 4 Simulations
- 5 Concluding remarks



Eguchi, Shoichi and Masuda, Hiroki (2024).

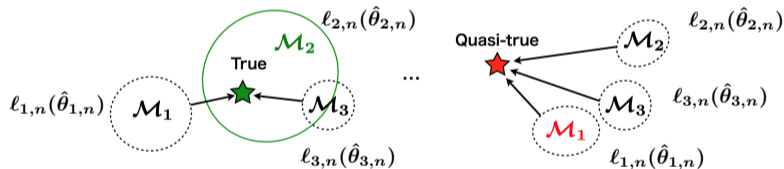
Gaussian quasi-information criteria for ergodic Lévy driven SDE.

Ann. Inst. Statist. Math., 76(1):111–157. (arXiv:2203.04039v3 (22 May, 2023))

AIC and BIC in general: Twin jewels of information criteria

- AIC and BIC are based on different philosophies, neither is absolutely better than the other:
 - AIC is designed for **predictive (generalization) performance**, while
 - BIC is for **model-description** performance.

How to relatively measure the discrepancy from the model to the (virtual) truth?



Avoid **over-fitting**
 \implies

$$\underbrace{-2\ell_n(\hat{\theta}_n)}_{\text{Goodness-of-fit}} + (\text{Complexity/Redundancy regularization})$$

Discrete-time setting, as a prelude

- Location-scale time series:

$$Y_j = a(Y_{j-1}, \alpha) + c(Y_{j-1}, \gamma)\epsilon_j, \quad \epsilon_1, \epsilon_2, \dots \stackrel{\text{i.i.d.}}{\sim} (0, 1)$$

- Gaussian (logarithmic) quasi-likelihood for estimating $\theta = (\alpha, \gamma)$:

$$\theta \mapsto \ell_n(\theta) := \sum_{j=1}^n \log \phi(Y_j; a(Y_{j-1}, \alpha), c(Y_{j-1}, \gamma)^2)$$

$$\xrightarrow{\text{Maximize}} \hat{\theta}_n = (\hat{\alpha}_n, \hat{\gamma}_n) \in \operatorname{argmax} \ell_n$$

$$\xrightarrow{\text{Regularity conditions}} \sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{\mathcal{L}} N(0, \Gamma(\theta_0)^{-1} \Sigma(\theta_0) \Gamma(\theta_0)^{-1})$$

$$\Rightarrow \text{Model assessment: } \begin{cases} \text{AIC} & -2\ell_n(\hat{\theta}_n) + 2 \operatorname{trace} \left(\Gamma(\hat{\theta}_n)^{-1} \Sigma(\hat{\theta}_n) \right) \\ \text{BIC} & -2\ell_n(\hat{\theta}_n) + (\log n) \dim \theta \end{cases}$$

“The” continuous-time counterpart of the abovementioned machinery?

1 Setup and objective

2 Estimation: GQMLE

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Objective

- Equally spaced high-frequency sample $\mathbf{X}_n = (X_{t_j^n})_{j=0}^n$ from **data-generating process**:

$$dX_t = C(X_{t-})dZ_t + A(X_t)dt \quad (1.1)$$

- $t_j^n = t_j = jh$, $T_n := nh \rightarrow \infty$, $nh^2 \rightarrow 0$ ($n \rightarrow \infty$)
 - $A: \mathbb{R}^d \rightarrow \mathbb{R}^d$ and $C: \mathbb{R}^d \rightarrow \mathbb{R}^d \otimes \mathbb{R}^r$
 - $Z = (Z_t)_{t \in \mathbb{R}_+}$ is an r -dimensional **non-Gaussian** Lévy process independent of X_0 .
- Correctly specified** statistical models \mathcal{M}_{m_1, m_2} for the unknown (1.1):

$$dX_t = c_{m_1}(X_{t-}, \gamma_{m_1})dZ_t + a_{m_2}(X_t, \alpha_{m_2})dt$$

- Scale** candidates $c_1(x, \gamma_1), \dots, c_{M_1}(x, \gamma_{M_1})$, $\gamma_{m_1} \in \Theta_{\gamma_{m_1}} \subset \mathbb{R}^{p_{\gamma_{m_1}}}$.
- Drift** candidates $a_1(x, \alpha_1), \dots, a_{M_2}(x, \alpha_{M_2})$, $\alpha_{m_2} \in \Theta_{\alpha_{m_2}} \subset \mathbb{R}^{p_{\alpha_{m_2}}}$.

Fully explicit **two-stage** inference based on the **Gaussian quasi-likelihood function (GQLF)**

Regularity conditions

- Omitting the model indices, we look at a single model:

$$dX_t = c(X_{t-}, \gamma)dZ_t + a(X_t, \alpha)dt$$

- Unknown parameter $\theta := (\alpha, \gamma)$: $\gamma = (\gamma_k) \in \Theta_\gamma \subset \mathbb{R}^{p_\gamma}$ and $\alpha = (\alpha_l) \in \Theta_\alpha \subset \mathbb{R}^{p_\alpha}$
- Let $\theta_0 = (\alpha_0, \gamma_0) \in \Theta := \Theta_\alpha \times \Theta_\gamma$ denote the true value of $\theta = (\alpha, \gamma)$.
- Scale matrix $S(x, \gamma) := c(x, \gamma)^{\otimes 2}$

- 1 **Moments** of the driving noise
- 2 **Smoothness and non-degeneracy** of the coefficients
- 3 **Stability**: exponential ergodicity and boundedness of moments
- 4 **Identifiability**

$$dX_t = c(X_{t-}, \gamma) dZ_t + a(X_t, \alpha) dt$$

Assumption 1.1 (Moments of driving noise)

$E[Z_1] = 0$, $E[Z_1^{\otimes 2}] = I_r$, and $E[|Z_1|^q] < \infty$ ($q > 0$).

- For $Z = \sigma^{1/2} w + J$, the pure-jump part J satisfies

$$\frac{1}{h} E \left[J_h^{(i_1)} \dots J_h^{(i_m)} \right] = \begin{cases} \nu_{i_1 i_2 i_3}(3) & m = 3, \\ \nu_{i_1 i_2 i_3 i_4}(4) + O(h) & m = 4, \end{cases}$$

where, for $m \geq 3$ and $z = (z_1, \dots, z_r)$,

$$\nu(m) = \{ \nu_{i_1 \dots i_m}(m) \}_{i_1, \dots, i_m} := \left\{ \int z_{i_1} \dots z_{i_m} \nu(dz) \right\}_{i_1, \dots, i_m}.$$

$$dX_t = c(X_{t-}, \gamma) dZ_t + a(X_t, \alpha) dt$$

Assumption 1.2 (Smoothness and non-degeneracy)

The coefficient $(x, \theta) \mapsto (a(x, \alpha), c(x, \gamma))$ is smooth enough:

- It is globally Lipschitz uniformly in $\theta \in \bar{\Theta}$;
- For some constant $C_{k,l} \geq 0$,

$$\max_{i \leq d} \max_{j,k} \sup_{\theta \in \bar{\Theta}} (|\partial_\alpha^j \partial_x^i a(x, \alpha)| + |\partial_\gamma^k \partial_x^i c(x, \gamma)|) \lesssim 1 + |x|^{C_{k,l}}$$

and moreover, $\sup_{\gamma \in \bar{\Theta}_\gamma} \lambda_{\min}\{S(x, \gamma)\}^{-1} \lesssim 1 + |x|^{C_0}$ for some constant $C_0 \geq 0$.

$$dX_t = c(X_{t-}, \gamma) dZ_t + a(X_t, \alpha) dt$$

Assumption 1.3 (Stability)

There exists a probability measure $\pi = \pi_{\theta_0}$ s.t. for every $q > 0$ there exists a positive constant a s.t.

$$\sup_{t \in \mathbb{R}_+} e^{at} \sup_{f: |f| \leq g} \left| \int f(y) P_t(x, dy) - \int f(y) \pi(dy) \right| \lesssim g(x), \quad x \in \mathbb{R}^d,$$

where $g(x) := 1 + \|x\|^q$. Further, $\sup_{t \in \mathbb{R}_+} E[|X_t|^q] < \infty$ for every $q > 0$,

- Several sufficient conditions are available: among others,
 - Meyn-Tweedie-theory based [Masuda, 2007]
 - Local Doeblin condition based [Kulik, 2009]
 - Monograph [Kulik, 2018] with systematic and detailed descriptions
 - ...

$$dX_t = c(X_{t-}, \gamma) dZ_t + a(X_t, \alpha) dt$$

Assumption 1.4 (Identifiability)

There exist positive constants χ_γ and χ_α such that for every γ and α ,

$$-\frac{1}{2} \int \left\{ \text{trace} (S(x, \gamma)^{-1} S(x, \gamma_0) - I_d) + \log \frac{|S(x, \gamma)|}{|S(x, \gamma_0)|} \right\} \pi(dx) \leq -\chi_\gamma |\gamma - \gamma_0|^2,$$

$$-\frac{1}{2} \int S^{-1}(x, \gamma_0) \left[(a(x, \alpha) - a(x, \alpha_0))^{\otimes 2} \right] \pi(dx) \leq -\chi_\alpha |\alpha - \alpha_0|^2.$$

- Different parameters should not lead to the same data-generating $\mathcal{L}(X)$.
- Essential in the **argmax** argument.

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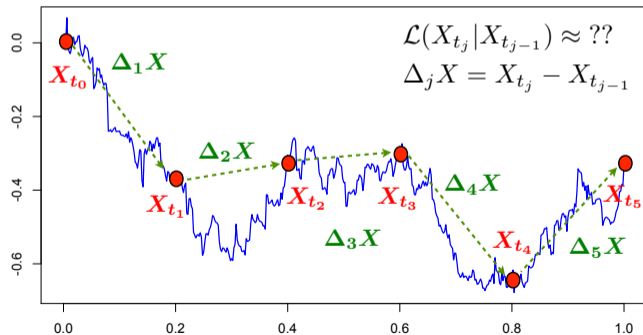
Advantage of stepwise estimation of the coefficients: scale \rightarrow trend

$$dX_t = c(X_{t-}, \gamma) dZ_t + a(X_t, \alpha) dt$$

Statistical problem, roughly

Find a reasonable alternative to the unknown genuine **log-likelihood**, formally given by

$$\log p_h(X_{t_1}, \dots, X_{t_n}; \theta) = \sum_{j=1}^n \log p_h(X_{t_{j-1}}, X_{t_j}; \theta)$$



Formulation of two-stage Gaussian quasi-likelihood estimation

- Write $\Delta_j Y = Y_{t_j} - Y_{t_{j-1}}$ and $f_{j-1}(\theta) = f(X_{t_{j-1}}, \theta)$.
- The Euler approximation for $dX_t = c(X_{t-}, \gamma)dZ_t + a(X_t, \alpha)dt$ under P_θ is given by

$$X_{t_j} \approx X_{t_{j-1}} + a_{j-1}(\alpha)h + c_{j-1}(\gamma)\Delta_j Z.$$

- Taking the small-time Gaussian approximation (**incorrect!**):

$$\mathcal{L}(X_{t_j} | X_{t_{j-1}} = x) \approx N_d(x + a(x, \alpha)h, hS(x, \gamma))$$

into account, we are led to the **joint** GQLF $\mathbb{H}_n(\theta) = \mathbb{H}_n(\mathbf{X}_n, \theta)$:

$$\begin{aligned} \mathbb{H}_n(\theta) &:= \sum_{j=1}^n \log \phi_d(X_{t_j}; X_{t_{j-1}} + a_{j-1}(\alpha)h, hS_{j-1}(\gamma)) \\ &= -\frac{1}{2} \sum_{j=1}^n \left(\log |2\pi h S_{j-1}(\gamma)| + \frac{1}{h} S_{j-1}^{-1}(\gamma) \left[(\Delta_j X - h a_{j-1}(\alpha))^{\otimes 2} \right] \right). \end{aligned} \quad (2.1)$$

- $\mathbb{H}_n(\theta) = \mathbb{H}_{1,n}(\gamma) + \mathbb{H}_{2,n}(\theta)$, where

$$\mathbb{H}_{1,n}(\gamma) := \sum_{j=1}^n \log \phi_d (X_{t_j}; X_{t_{j-1}}, hS_{j-1}(\gamma)),$$

$$\mathbb{H}_{2,n}(\theta) := \sum_{j=1}^n \left(S_{j-1}^{-1}(\gamma) [\Delta_j X, a_{j-1}(\alpha)] - \frac{h}{2} S_{j-1}^{-1}(\gamma) [a_{j-1}^{\otimes 2}(\alpha)] \right)$$

have two different resolutions: $n^{-1}\mathbb{H}_{1,n}(\gamma)$ and $T_n^{-1}\mathbb{H}_{2,n}(\theta)$ have proper LLN limits.

- The following **two-stage** estimation strategy is natural (Gaussian quasi-MLE: **GQMLE**):
 - 1 Estimate γ by $\hat{\gamma}_n \in \operatorname{argmax}_{\gamma} \mathbb{H}_{1,n}(\gamma)$;
 - 2 Estimate α by $\hat{\alpha}_n \in \operatorname{argmax}_{\alpha} \mathbb{H}_{2,n}(\alpha)$ where, with a slight abuse of notation:

$$\mathbb{H}_{2,n}(\alpha) := \mathbb{H}_{2,n}(\alpha, \hat{\gamma}_n).$$

Theorem 2.1 (Mighty convergence of the GQMLE [Eguchi and Masuda, 2024])

Under Assumptions 1.1, 1.2, 1.3, and 1.4, we have the convergence of moments for any continuous function $f : \mathbb{R}^p \rightarrow \mathbb{R}$ of at most polynomial growth:

$$E \left[f \left(\sqrt{T_n}(\hat{\theta}_n - \theta_0) \right) \right] \rightarrow \int f(u) \phi(u; 0, V(\theta_0)) du$$

with $V(\theta_0) = \Gamma(\theta_0)^{-1} \Sigma(\theta_0) \Gamma(\theta_0)^{-1}$ explicitly given, hence in particular:

- $\hat{u}_n := \sqrt{T_n}(\hat{\theta}_n - \theta_0) \xrightarrow{\mathcal{L}} N_p(0, V(\theta_0));$
- $E[\hat{u}_n] \rightarrow 0$, $E[\hat{u}_n^{\otimes 2}] \rightarrow V(\theta_0)$, and also $\sup_n E[|\hat{u}_n|^q] < \infty$ for every $q > 0$.

Further, it is possible to construct an explicit consistent estimator $\hat{V}_n \xrightarrow{P} V(\theta_0)$, so that

$$\hat{V}_n^{-1/2} \sqrt{T_n}(\hat{\theta}_n - \theta_0) \xrightarrow{\mathcal{L}} N_p(0, I_p).$$

Related remarks

- **Dividing estimation stages does not change asymptotic covariance.**

Comparing Theorem 2.1 and [Masuda, 2013, Theorem 2.7] shows that the joint and stepwise GQMLE have the same asymptotic distribution.

$$\mathbb{H}_n(\theta) = \sum_{j=1}^n \log \phi_d (X_{t_j}; X_{t_{j-1}} + a_{j-1}(\alpha)h, hS_{j-1}(\gamma)) = \mathbb{H}_{1,n}(\gamma) + \mathbb{H}_{2,n}(\theta),$$

$$\mathbb{H}_{1,n}(\gamma) = \sum_{j=1}^n \log \phi_d (X_{t_j}; X_{t_{j-1}}, hS_{j-1}(\gamma)),$$

$$\mathbb{H}_{2,n}(\theta) = \sum_{j=1}^n \left(S_{j-1}^{-1}(\gamma) [\Delta_j X, a_{j-1}(\alpha)] - \frac{h}{2} S_{j-1}^{-1}(\gamma) [a_{j-1}^{\otimes 2}(\alpha)] \right)$$

- **Simpler form for the univariate case** ($d = r = 1$) for $V(\theta_0) = \Gamma(\theta_0)^{-1}\Sigma(\theta_0)\Gamma(\theta_0)^{-1}$:

$$\Sigma(\theta_0) = \begin{pmatrix} \Gamma_\alpha(\theta_0) & W_{\alpha,\gamma}(\theta_0) \\ W_{\alpha,\gamma}(\theta_0)^\top & W_\gamma(\gamma_0) \end{pmatrix}, \quad \Gamma(\theta_0) = \text{diag}\{\Gamma_\alpha(\theta_0), \Gamma_\gamma(\gamma_0)\}.$$

$$\Gamma_\alpha(\theta_0) = \int \left(\frac{\partial_\alpha a(x, \alpha_0)}{c(x, \gamma_0)} \right)^{\otimes 2} \pi(dx), \quad \Gamma_\gamma(\gamma_0) = \frac{1}{2} \int \left(\frac{\partial_\gamma S(x, \gamma_0)}{S(x, \gamma_0)} \right)^{\otimes 2} \pi(dx).$$

$$W_{\alpha,\gamma}(\theta_0) = \frac{1}{2} \nu(3) \int \frac{(\partial_\gamma S) \otimes (\partial_\alpha a)}{c^3}(x, \theta_0) \pi(dx),$$

$$W_\gamma(\gamma_0) = \frac{1}{4} \nu(4) \int \left(\frac{\partial_\gamma S(x, \gamma_0)}{S(x, \gamma_0)} \right)^{\otimes 2} \pi(dx) = \frac{\nu(4)}{2} \Gamma_\gamma(\gamma_0).$$

- Multivariate case involves many multil-linear forms, notationally messy.

- **The Studentization**

$$\hat{V}_n^{-1/2} \sqrt{T_n} (\hat{\theta}_n - \theta_0) \xrightarrow{\mathcal{L}} N_p(0, I_p).$$

automatically distinguish “diffusion or Lévy with jumps”.

The well-known fact $D_n(\hat{\theta}_n - \theta_0) \xrightarrow{\mathcal{L}} N_p(0, \Gamma(\theta_0)^{-1})$ with the different (partly faster) rate of convergence $D_n := \text{diag}(\sqrt{T_n} I_{p_\alpha}, \sqrt{n} I_{p_\gamma})$, see [Kessler, 1997] and [Uchida and Yoshida, 2012]:

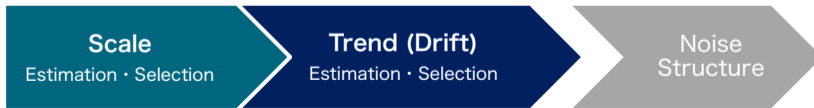
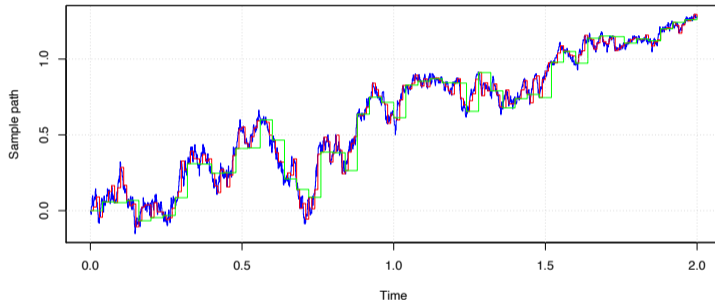
$$\begin{aligned} \hat{V}_n^{-1/2} \sqrt{T_n} (\hat{\theta}_n - \theta_0) &= \left(\sqrt{T_n} \hat{V}_n D_n^{-1} \right) D_n (\hat{\theta}_n - \theta_0), \\ \sqrt{T_n} \hat{V}_n D_n^{-1} &\xrightarrow{P} \Gamma(\theta_0)^{1/2}, \end{aligned}$$

resulting in

$$\left(\sqrt{T_n} (\hat{\alpha}_n - \alpha_0), \sqrt{n} (\hat{\gamma}_n - \gamma_0) \right) \xrightarrow{\mathcal{L}} N_p(0, \Gamma(\theta_0)^{-1}).$$

- Next section: Relative model comparison through AIC and BIC philosophies.

$$X_{t+dt} \leftarrow X_t + (\text{Trend})dt + (\text{Scale}) \cdot d(\text{Noise})$$



Summary: GQMLE for ergodic Lévy SDE

$$dX_t = C(X_{t-})dZ_t + A(X_t)dt$$

$$\mathbf{X}_n = (X_{t_j^n})_{j=0}^n$$

$$t_j^n = t_j = jh, \quad T_n := nh \rightarrow \infty, \quad nh^2 \rightarrow 0 \quad (n \rightarrow \infty)$$



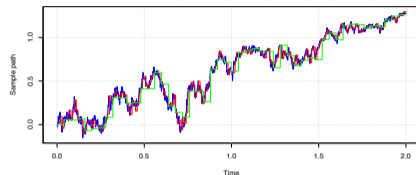
$$X_{t_j} \approx X_{t_{j-1}} + a_{j-1}(\alpha)h + c_{j-1}(\gamma)\Delta_j Z.$$

$$\mathbb{H}_n(\theta) = \sum_{j=1}^n \log \phi_d(X_{t_j}; X_{t_{j-1}} + a_{j-1}(\alpha)h, hS_{j-1}(\gamma)) = \mathbb{H}_{1,n}(\gamma) + \mathbb{H}_{2,n}(\theta)$$

$$\mathbb{H}_{1,n}(\gamma) = \sum_{j=1}^n \log \phi_d(X_{t_j}; X_{t_{j-1}}, hS_{j-1}(\gamma)),$$

$$\mathbb{H}_{2,n}(\theta) = \sum_{j=1}^n \left(S_{j-1}^{-1}(\gamma) [\Delta_j X, a_{j-1}(\alpha)] - \frac{h}{2} S_{j-1}^{-1}(\gamma) [a_{j-1}^{\otimes 2}(\alpha)] \right)$$

$$X_{t+dt} \leftarrow X_t + (\text{Trend})dt + (\text{Scale}) \cdot d(\text{Noise})$$



$$E \left[f \left(\sqrt{T_n}(\hat{\theta}_n - \theta_0) \right) \right] \rightarrow \int f(u) \phi(u; 0, V(\theta_0)) du$$

$$\hat{V}_n^{-1/2} \sqrt{T_n}(\hat{\theta}_n - \theta_0) \xrightarrow{\mathcal{L}} N_p(0, I_p)$$



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- **Correctly specified** statistical models \mathcal{M}_{m_1, m_2} ($m_1 \leq M_1$; $m_2 \leq M_2$):

$$dX_t = c_{m_1}(X_{t-}, \gamma_{m_1})dZ_t + a_{m_2}(X_t, \alpha_{m_2})dt,$$

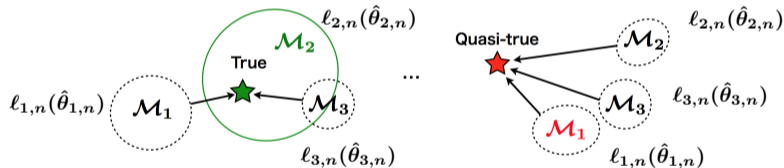
$$\text{e.g. } dX_t = \exp\left(\frac{1}{2} \sum_{k=1}^{p_\gamma} \gamma_k S_k(X_{t-})\right) dZ_t + \sum_{l=1}^{p_\alpha} \alpha_l a_l(X_{t-}) dt$$

- Akaike's AIC type and Schwarz's BIC type statistics for ergodic Lévy SDE?
- **Stepwise** selection strategy of the coefficients would be **essential**: scale \rightarrow trend.

AIC and BIC in general: Twin jewels of information criteria (reprint)

- AIC and BIC are based on different philosophies, neither is absolutely better than the other:
 - AIC is designed for **predictive (generalization) performance**, while
 - BIC is for **model-description** performance.

How to relatively measure the discrepancy from the model to the (virtual) truth?



Avoid **over-fitting**
 \implies

$$\underbrace{-2\ell_n(\hat{\theta}_n)}_{\text{Goodness-of-fit}} + (\text{Complexity/Redundancy regularization})$$

Preliminary general remarks on **AIC** paradigm

- True distribution $g(x)\mu(x)$ of a sample $\mathbf{X}_n \leftarrow$ Statistical model $\{f(\cdot; \theta) : \theta \in \Theta\}$ wrt μ .
- Estimate g by $\hat{f}_n(\cdot) = f(\cdot; \hat{\theta}_n)$ for some $\hat{\theta}_n = \hat{\theta}_n(\mathbf{X}_n)$.
- Minimize the **Kullback-Leibler divergence**

$$\mathcal{D}(\hat{f}_n; g) = \left(\int g \log \left(\frac{g}{\hat{f}_n} \right) g d\mu \right) \Big|_{f_n = \hat{f}_n}.$$

- It amounts to minimizing the relative entropy $\mathcal{E}(\hat{f}_n; g)$ where $\mathcal{E}(f; g) := - \int (\log f) g d\mu$.
- As g is unknown, we substitute the empirical counterpart $\mathcal{E}(\hat{f}_n; \delta_{\mathbf{X}_n})$ for $\mathcal{E}(\hat{f}_n; g)$.
- Then, by removing the randomness by integrating out \mathbf{X}_n with respect to g , it is desired to derive a **computable corrector** \hat{b}_n such that

$$E \left[\mathcal{E}(\hat{f}_n; g) - \left(\mathcal{E}(\hat{f}_n; \delta_{\mathbf{X}_n}) + \hat{b}_n \right) \right] = o(1), \quad n \rightarrow \infty. \quad (3.1)$$

- Put simply: derivation of AIC amounts to managing this expectation.

- The routine way is to first compute the “reading” term(s) of

$$\mathfrak{b}_n := E \left[\mathcal{E}(\hat{f}_n; g) - \mathcal{E}(\hat{f}_n; \delta \mathbf{X}_n) \right],$$

and then construct an asymptotically unbiased estimator $\hat{\mathfrak{b}}_n = \hat{\mathfrak{b}}_n(\mathbf{X}_n)$, i.e. $E[\hat{\mathfrak{b}}_n - \mathfrak{b}_n] = o(1)$.

- For models regular enough, we very often reach

$$\hat{\mathfrak{b}}_n = \dim(\text{Unknown parameters}).$$

The above strategy can be traced (formally makes sense)

- whatever the probabilistic structure of $\mathcal{L}(\mathbf{X}_n)$ is, and
- when the model $\{f(\cdot; \theta) : \theta \in \Theta\}$ is misspecified.

What's essential therein is that we can find a suitable corrector $\hat{\mathfrak{b}}_n$ satisfying the property (3.1).

Approximation of bias in joint case?

- Turning back to our setup, we keep considering the SDE model (index (m_1, m_2) omitted):

$$dX_t = c(X_{t-}, \gamma)dZ_t + a(X_t, \alpha)dt.$$

- If we try to evaluate the bias directly for the joint GQMLE $\mathbb{H}_n(\theta)$, as

$$\begin{aligned} \mathfrak{b}_n &:= E \left[\mathbb{H}_n(\hat{\theta}_n(\mathbf{X}_n); \mathbf{X}_n) - \tilde{E} \left[\tilde{\mathbb{H}}_n(\hat{\theta}_n(\mathbf{X}_n); \tilde{\mathbf{X}}_n) \right] \right] \quad (\tilde{\mathbf{X}}_n \text{ is an indep. copy of } \mathbf{X}_n) \\ &=: E \tilde{E} \left[\left(\mathbb{H}_n(\hat{\theta}_n) - \mathbb{H}_n(\theta_0) \right) - \left(\tilde{\mathbb{H}}_n(\hat{\theta}_n) - \tilde{\mathbb{H}}_n(\theta_0) \right) \right], \end{aligned}$$

we need to look at the identity:

$$\mathbb{H}_n(\hat{\theta}_n) - \mathbb{H}_n(\theta_0) = \mathbb{H}_{1,n}(\hat{\gamma}_n) - \mathbb{H}_{1,n}(\gamma_0) + \mathbb{H}_{2,n}(\hat{\alpha}_n, \hat{\gamma}_n) - \mathbb{H}_{2,n}(\alpha_0, \gamma_0) = \frac{1}{h} \mathcal{Q}_{1,n}(\gamma_0) + \mathcal{Q}_{2,n}(\theta_0). \quad (3.2)$$

- Importantly, both $\mathcal{Q}_{1,n}(\gamma_0)$ and $\mathcal{Q}_{2,n}(\theta_0)$ are the asymptotically non-trivial;
- while $\mathbb{H}_n(\hat{\theta}_n) - \mathbb{H}_n(\theta_0) = O_p(1)$ in case of diffusions.

- Let $\hat{u}_n := (\hat{u}_{\alpha,n}, \hat{u}_{\gamma,n})$ where $\hat{u}_{\gamma,n} := \sqrt{T_n}(\hat{\gamma}_n - \gamma_0)$ and $\hat{u}_{\alpha,n} := \sqrt{T_n}(\hat{\alpha}_n - \alpha_0)$.
- Roughly, under suitable regularity conditions we may write

$$\mathbb{H}_n(\hat{\theta}_n) - \mathbb{H}_n(\theta_0) = \sum_{k \in \mathbb{N}} \frac{1}{k!} \underbrace{\left\{ \left(\frac{1}{n} \partial_{\theta}^k \mathbb{H}_n(\theta_0) \right) [\hat{u}_n^{\otimes k}] \right\}}_{\substack{= O_p(1) \ (\neq o_p(1)) \\ \text{for } \partial_{\gamma}^k \text{-components}}} n T_n^{-k/2}.$$

- $n T_n^{-k/2} \rightarrow 0$ only for k large enough (will lead to messy and unpleasant terms!).
- In case of diffusions, $\mathbb{H}_n(\hat{\theta}_n) - \mathbb{H}_n(\theta_0)$ itself is of the log-likelihood ratio type character.
- The **mixed-rates structure** necessitates the higher-order derivatives of \mathbb{H}_n in the direct evaluation of b_n based on the **joint** GQLF $\mathbb{H}_n(\theta)$, resulting in **rather complicated expressions**.

We can bypass this issue through the **two-stage** GQLF $\mathbb{H}_{1,n}(\gamma)$ and $\mathbb{H}_{2,n}(\alpha)$: in other words, we're going to **separately** look at the two terms $\mathcal{Q}_{1,n}(\gamma_0)$ and $\mathcal{Q}_{2,n}(\theta_0)$ in (3.2) **in this order**.

$$\mathbb{H}_n(\hat{\theta}_n) - \mathbb{H}_n(\theta_0) \frac{1}{h} \mathcal{Q}_{1,n}(\gamma_0) + \mathcal{Q}_{2,n}(\theta_0).$$

Stepwise bias corrections

- 1 **Scale:** $\mathcal{Q}_{1,n}(\gamma_0)$ -part AIC-bias (w.r.t. γ) is

$$\begin{aligned} \mathfrak{b}_{\gamma,n} &:= hE \left[\mathbb{H}_{1,n}(\hat{\gamma}_n(\mathbf{X}_n); \mathbf{X}_n) - \tilde{E} \left[\tilde{\mathbb{H}}_{1,n}(\hat{\gamma}_n(\mathbf{X}_n); \tilde{\mathbf{X}}_n) \right] \right] \\ &= \text{trace} \left\{ \Gamma_\gamma(\gamma_0)^{-1} W_\gamma(\gamma_0) \right\} + O(T_n^{-1/2}). \end{aligned} \quad (3.3)$$

with both $\Gamma_\gamma(\gamma_0)$ and $W_\gamma(\gamma_0)$ being explicit: plugging-in their estimates,

$$\text{GQAIC}_{1,n} := -2 \mathbb{H}_{1,n}(\hat{\gamma}_n) + \frac{2}{h} \text{trace} \left(\hat{\Gamma}_{\gamma,n}^{-1} \hat{W}_{\gamma,n} \right). \quad (3.4)$$

- The particular case of $d = r = 1$:

$$\text{GQAIC}_{1,n} = -2 \mathbb{H}_{1,n}(\hat{\gamma}_n) + \frac{1}{h} \hat{\nu}_n(4) \rho_\gamma, \quad \hat{\nu}_n(4) := \frac{1}{T_n} \sum_{j=1}^n \left(\frac{\Delta_j X}{c_{j-1}(\hat{\gamma}_n)} \right)^4 \xrightarrow{P} \nu(4) := \int z^4 \nu(dz).$$

A finite-sample correction is possible to make the formula consistent with the diffusion case.

- Having the estimate $\hat{\gamma}_n$ in hand, we proceed to the bias evaluation for the drift coefficient.
- ② **Drift:** $Q_{2,n}(\theta_0)$ -part AIC-bias (w.r.t. α) turned out to be

$$\begin{aligned} \mathfrak{b}_{\alpha,n} &:= E \left[\mathbb{H}_{2,n}(\hat{\alpha}_n, \hat{\gamma}_n) - \tilde{E} \left[\tilde{\mathbb{H}}_{2,n}(\hat{\alpha}_n, \hat{\gamma}_n) \right] \right] \\ &= p_\alpha + \mathfrak{b}_{A,n} + o(1), \end{aligned} \quad (3.5)$$

with the term $\mathfrak{b}_{A,n}$ being common to all the drift-coefficient candidate, so that we may and do ignore $\mathfrak{b}_{A,n}$ in *relative* model comparison, for it is common to all the candidates:

$$\text{GQAIC}_{2,n} := -2 \mathbb{H}_{2,n}(\hat{\alpha}_n) + 2p_\alpha. \quad (3.6)$$

Theorem 3.1 (GQAIC formula for ergodic Lévy SDE: [Eguchi and Masuda, 2024])

Suppose additionally that $E \left[\text{trace} \left(\hat{\Gamma}_{\gamma,n}^{-1} \hat{W}_{\gamma,n} \right) \right] \rightarrow \text{trace} \{ \Gamma_\gamma(\gamma_0)^{-1} W_\gamma(\gamma_0) \}$. Then, the approximation (3.3) and (3.5) hold.

- **Correctly specified** statistical models \mathcal{M}_{m_1, m_2} ($m_1 \leq M_1$; $m_2 \leq M_2$):

$$dX_t = c_{m_1}(X_{t-}, \gamma_{m_1}) dZ_t + a_{m_2}(X_t, \alpha_{m_2}) dt.$$

$$\mathbb{H}_{1,n}(\gamma) = \sum_{j=1}^n \log \phi_d(X_{t_j}; X_{t_{j-1}}, hS_{j-1}(\gamma)),$$

$$\mathbb{H}_{2,n}(\theta) = \sum_{j=1}^n \left(S_{j-1}^{-1}(\gamma) [\Delta_j X, a_{j-1}(\alpha)] - \frac{h}{2} S_{j-1}^{-1}(\gamma) [a_{j-1}^{\otimes 2}(\alpha)] \right)$$

Our proposal for how to select the scale coefficient through AIC

- 1 FIRST select the scale by (3.4): $\text{GQAIC}_{1,n} := -2 \mathbb{H}_{1,n}(\hat{\gamma}_n) + \frac{2}{h} \text{trace} \left(\hat{\Gamma}_{\gamma,n}^{-1} \hat{W}_{\gamma,n} \right)$
- 2 THEN select the drift by (3.6): $\text{GQAIC}_{2,n} := -2 \mathbb{H}_{2,n}(\hat{\alpha}_n) + 2p_\alpha$.
 - For the GQAIC, the prob. of “underestimating model” goes to 0.

Remark 3.2 (GQAIC for diffusion)

$$dX_t = c(X_{t-}, \gamma)dw_t + a(X_t, \alpha)dt$$

- GQAIC become $-2\mathbb{H}_{1,n}(\hat{\gamma}_n) + 2p_\gamma$ for scale, and $-2\mathbb{H}_{2,n}(\hat{\alpha}_n) + 2p_\alpha$ for drift.
- Moreover, in case of the joint estimation through the GQLF $\mathbb{H}_n(\theta)$ of (2.1), the GQAIC is

$$-2\mathbb{H}_n(\hat{\theta}_n) + 2(p_\alpha + p_\gamma),$$

the same form as in the CIC of [Uchida, 2010], the contrast information criterion.

- The source of this essential difference is that, for diffusions, the statistical random fields is *jointly* LAQ.

Preliminary remarks on **BIC** paradigm

$$dX_t = c(X_{t-}, \gamma) dZ_t + a(X_t, \alpha) dt.$$

- BIC methodology is to select the model that approximately minimizes the minus logarithmic **model evidence** defined to be, with $\pi(\theta)$ denoting the joint prior density of (α, γ) ,

$$-\log \left(\int_{\Theta} \exp\{\mathbb{H}_n(\theta)\} \pi(\theta) d\theta \right)$$

for the **joint** GQLF. As in the GQAIC case, we formulate a **stepwise** procedure.

- We keep using the two-stage GQLFs $\mathbb{H}_{1,n}(\gamma)$ and $\mathbb{H}_{2,n}(\alpha) = \mathbb{H}_{2,n}(\alpha, \hat{\gamma}_n)$.
- In addition, we consider the **prior densities** $\pi_1(\gamma)$ and $\pi_2(\alpha)$ for α and γ , respectively.
 - We assume that both π_1 and π_2 are continuous and bounded in $\bar{\Theta}_\gamma$ and $\bar{\Theta}_\alpha$ respectively, and moreover that $\pi_1(\gamma_0) > 0$ and $\pi_2(\alpha_0) > 0$.
- We additionally assume that there exists a constant $c_1 \in (0, 1)$ for which $T_n \gtrsim n^{c_1}$.

Stepwise stochastic expansions

- ① **Scale: Free energy at the inverse temperature** $\mathfrak{b} > 0$, defined through the negative normalized logarithmic partition function:

$$\mathfrak{F}_{1,n}(\mathfrak{b}) := -\frac{1}{n\mathfrak{b}} \log \left(\int_{\Theta_\gamma} \exp\{\mathfrak{b} \mathbb{H}_{1,n}(\gamma)\} \pi_1(\gamma) d\gamma \right).$$

- The terminology “normalized” means that $\mathfrak{F}_{1,n}(\mathfrak{b})$ has non-trivial limit (in probability) for each $\mathfrak{b} > 0$; the normalized marginal quasi-log likelihood corresponds to $\mathfrak{F}_{1,n}(1)$.
- The classical BIC methodology is based on a stochastic expansion of $\mathfrak{F}_{1,n}(1)$; see [Eguchi and Masuda, 2018] and the references therein.
- $\mathfrak{F}_{1,n}(1)$ quantifies the minus model evidence for the $Q_{1,n}(\gamma_0)$ -part: a smaller $\mathfrak{F}_{1,n}(1)$ is **better in model description**.

$$\mathfrak{F}_{1,n}(\mathbf{b}) := -\frac{1}{n\mathbf{b}} \log \left(\int_{\Theta_\gamma} \exp\{\mathbf{b} \mathbb{H}_{1,n}(\gamma)\} \pi_1(\gamma) d\gamma \right).$$

Theorem 3.3 (Scale-QBIC formula for ergodic Lévy SDE: [Eguchi and Masuda, 2024])

$$\mathfrak{F}_{1,n}(1) = -\frac{1}{n} \mathbb{H}_{1,n}(\hat{\gamma}_n) + \frac{p_\gamma}{2n} \log n + O_p \left(\frac{1}{n} \right), \quad (3.7)$$

$$\mathfrak{F}_{1,n}(h) = -\frac{1}{n} \mathbb{H}_{1,n}(\hat{\gamma}_n) + \frac{p_\gamma}{2T_n} \log T_n + O_p \left(\frac{1}{T_n} \right). \quad (3.8)$$

- The first one (3.7) was previously given in [Eguchi and Uehara, 2021], based on which the QBIC for the scale was defined to be $-2\mathbb{H}_{1,n}(\hat{\gamma}_n) + p_\gamma \log n$.
- For the **model-selection consistency** to be in force, we propose to adopt (3.8):

$$\text{GQBIC}_{1,n} = -2 \mathbb{H}_{1,n}(\hat{\gamma}_n) + \frac{p_\gamma}{h} \log T_n. \quad (3.9)$$

- ② **Drift:** We can directly look at the normalized marginal quasi-log likelihood

$$\mathfrak{F}_{2,n} = \mathfrak{F}_{2,n}(1) := -\frac{1}{T_n} \log \left(\int_{\Theta_\alpha} \exp\{\mathbb{H}_{2,n}(\alpha)\} \pi_2(\alpha) d\alpha \right).$$

Theorem 3.4 (Drift-GQBIC formula for ergodic Lévy SDE: [Eguchi and Masuda, 2024])

$$\mathfrak{F}_{2,n}(1) = -\frac{1}{T_n} \mathbb{H}_{2,n}(\hat{\alpha}_n) + \frac{p_\alpha}{2T_n} \log T_n + O_p \left(\frac{1}{T_n} \right).$$

- Ignoring $O_p(T_n^{-1})$ of $\mathfrak{F}_{2,n}$ (as in [Eguchi and Masuda, 2018]), we introduce the second GQBIC:

$$\text{GQBIC}_{2,n} = -2 \mathbb{H}_{2,n}(\hat{\alpha}_n) + p_\alpha \log T_n. \quad (3.10)$$

- **Correctly specified** statistical models \mathcal{M}_{m_1, m_2} ($m_1 \leq M_1$; $m_2 \leq M_2$):

$$dX_t = c_{m_1}(X_{t-}, \gamma_{m_1}) dZ_t + a_{m_2}(X_t, \alpha_{m_2}) dt.$$

$$\mathbb{H}_{1,n}(\gamma) = \sum_{j=1}^n \log \phi_d(X_{t_j}; X_{t_{j-1}}, hS_{j-1}(\gamma)),$$

$$\mathbb{H}_{2,n}(\theta) = \sum_{j=1}^n \left(S_{j-1}^{-1}(\gamma) [\Delta_j X, a_{j-1}(\alpha)] - \frac{h}{2} S_{j-1}^{-1}(\gamma) [a_{j-1}^{\otimes 2}(\alpha)] \right)$$

Our proposal for how to select the scale coefficient through BIC

① FIRST select the scale by (3.9): $\text{GQBIC}_{1,n} = -2 \mathbb{H}_{1,n}(\hat{\gamma}_n) + \frac{p_\gamma}{h} \log T_n.$

② THEN select the drift by (3.10): $\text{GQBIC}_{2,n} = -2 \mathbb{H}_{2,n}(\hat{\alpha}_n) + p_\alpha \log T_n.$

- The **selection consistency** follows as in [Eguchi and Masuda, 2018] or [Eguchi and Masuda, 2019].

- 1 Setup and objective
- 2 Estimation: GQMLE
- 3 Selection: GQAIC and GQBIC
- 4 Simulations**
- 5 Concluding remarks

Simulation design

$$dX_t = -\frac{1}{2}X_t dt + \frac{3}{1 + X_t^2} dZ_t, \quad t \in [0, T_n], \quad X_0 = 0.$$

- Three different noises:

- (i) Normal inverse Gaussian noise $\mathcal{L}(Z_t) = \text{NIG}(10, 0, 10t, 0)$,
- (ii) Normal bilateral gamma noise $\mathcal{L}(Z_t) = \text{bGamma}(t, \sqrt{2}, t, \sqrt{2})$,
- (iii) Skewed NIG noise $\mathcal{L}(Z_t) = \text{NIG}(\frac{25}{3}, \frac{20}{3}, \frac{9}{5}t, -\frac{12}{5}t)$.

- We use YUIMA R package [Brouste et al., 2014] for generating data.
- Monte Carlo trials are based on 1000 independent sample paths, done for

$$(h_n, T_n) = (0.01, 10), (0.005, 10), (0.01, 50), \text{ and } (0.005, 50),$$

hence in each case, $n = 1000, 2000, 5000$, and 10000 .

$$dX_t = -\frac{1}{2}X_t dt + \frac{3}{1+X_{t-}^2} dZ_t, \quad t \in [0, T_n], \quad X_0 = 0.$$

- Candidate scale (Scale) and drift (Drift) coefficients:

- Scale 1 : $c_1(x, \gamma_1) = \gamma_1$

- Scale 2 : $c_2(x, \gamma_2) = \frac{\gamma_2}{1+x^2}$

- Scale 3 : $c_3(x, \gamma_3) = \frac{\gamma_{3,1} + \gamma_{3,2}x^2}{1+x^2}$

- Scale 4 : $c_4(x, \gamma_4) = \frac{\gamma_{4,1} + \gamma_{4,2}x + \gamma_{4,3}x^2}{1+x^2}$

- Drift 1 : $a_1(x, \alpha_1) = -\alpha_1$

- Drift 2 : $a_2(x, \alpha_2) = -\alpha_2 x$

- Drift 3 : $a_3(x, \alpha_3) = -\alpha_{3,1}x - \alpha_{3,2}$

- Then, the optimal (minimal true) model consists of Scale 2 and Drift 2 with $(\gamma_2, \alpha_2) = (3, \frac{1}{2})$.

- The proposed information criteria (with non-essential modification for $\text{GQAIC}_{1,n}$):

$$\text{CIC}_{1,n} = -2\mathbb{H}_{1,n}(\hat{\gamma}_n) + 2p_\gamma, \quad \text{CIC}_{2,n} = -2\mathbb{H}_{2,n}(\hat{\alpha}_n) + 2p_\alpha,$$

(Calculated just for comparison)

$$\text{GQAIC}_{1,n} = -2\mathbb{H}_{1,n}(\hat{\gamma}_n) + p_\gamma \left\{ \frac{1}{hT_n} \sum_{j=1}^n \left(\frac{\Delta_j X}{c_{j-1}(\hat{\gamma}_n)} \right)^4 - \left(\frac{1}{T_n} \sum_{j=1}^n \left(\frac{\Delta_j X}{c_{j-1}(\hat{\gamma}_n)} \right)^2 \right)^2 \right\},$$

$$\text{GQAIC}_{2,n} = -2\mathbb{H}_{2,n}(\hat{\alpha}_n) + 2p_\alpha,$$

$$\text{GQBIC}_{1,n}^\# = -2\mathbb{H}_{1,n}(\hat{\gamma}_n) + p_\gamma \log n, \quad \text{QBIC}_{1,n} = -2\mathbb{H}_{1,n}(\hat{\gamma}_n) + \frac{p_\gamma}{h_n} \log T_n,$$

$$\text{QBIC}_{2,n} = -2\mathbb{H}_{2,n}(\hat{\alpha}_n) + p_\alpha \log T_n.$$

Model-selection frequencies in (i) $\mathcal{L}(Z_t) = NIG(10, 0, 10t, 0)$

CIC	T_n	h_n		Scale 1	Scale 2*	Scale 3	Scale 4
10 ($n = 1000$)	0.01	Drift 1		0	1	0	0
			Drift 2*	0	536	124	199
			Drift 3	0	74	27	39
10 ($n = 2000$)	0.005	Drift 1		0	0	1	0
			Drift 2*	0	458	110	285
			Drift 3	0	67	25	54
50 ($n = 5000$)	0.01	Drift 1		0	0	0	0
			Drift 2*	0	466	202	231
			Drift 3	0	51	28	32
50 ($n = 10000$)	0.005	Drift 1		0	0	0	0
			Drift 2*	0	402	150	352
			Drift 3	0	51	13	32

GQAIC	T_n	h_n		Scale 1	Scale 2*	Scale 3	Scale 4
10 ($n = 1000$)	0.01	Drift 1		0	1	0	0
			Drift 2*	0	714	77	64
			Drift 3	0	110	20	14
10 ($n = 2000$)	0.005	Drift 1		0	1	0	0
			Drift 2*	0	733	62	56
			Drift 3	0	117	17	14
50 ($n = 5000$)	0.01	Drift 1		0	0	0	0
			Drift 2*	0	713	122	64
			Drift 3	0	83	11	7
50 ($n = 10000$)	0.005	Drift 1		0	0	0	0
			Drift 2*	0	765	79	59
			Drift 3	0	88	5	4

QBIC	T_n	h_n		Scale 1	Scale 2*	Scale 3	Scale 4
10 ($n = 1000$)	0.01	Drift 1		0	1	0	0
			Drift 2*	0	861	0	0
			Drift 3	0	138	0	0
10 ($n = 2000$)	0.005	Drift 1		0	1	0	0
			Drift 2*	0	866	0	0
			Drift 3	0	133	0	0
50 ($n = 5000$)	0.01	Drift 1		0	0	0	0
			Drift 2*	0	965	0	0
			Drift 3	0	35	0	0
50 ($n = 10000$)	0.005	Drift 1		0	0	0	0
			Drift 2*	0	964	0	0
			Drift 3	0	36	0	0

GQBIC [#]	T_n	h_n		Scale 1	Scale 2*	Scale 3	Scale 4
10 ($n = 1000$)	0.01	Drift 1		0	1	0	0
			Drift 2*	0	788	49	30
			Drift 3	0	119	7	6
10 ($n = 2000$)	0.005	Drift 1		0	1	0	0
			Drift 2*	0	759	69	45
			Drift 3	0	107	9	10
50 ($n = 5000$)	0.01	Drift 1		0	0	0	0
			Drift 2*	0	882	64	19
			Drift 3	0	32	2	1
50 ($n = 10000$)	0.005	Drift 1		0	0	0	0
			Drift 2*	0	862	68	34
			Drift 3	0	32	2	2

Model-selection frequencies in (ii) $\mathcal{L}(Z_t) = b\text{Gamma}(t, \sqrt{2}, t, \sqrt{2})$

CIC	T_n	h_n		Scale 1	Scale 2*	Scale 3	Scale 4	
10	0.01	Drift 1		0	0	0	9	
			($n = 1000$)	Drift 2*	5	106	26	767
			Drift 3	0	10	1	76	
10	0.005	Drift 1		0	0	0	9	
			($n = 2000$)	Drift 2*	2	83	24	793
			Drift 3	0	6	2	81	
50	0.01	Drift 1		0	0	0	0	
			($n = 5000$)	Drift 2*	2	85	47	782
			Drift 3	0	6	4	74	
50	0.005	Drift 1		0	0	0	0	
			($n = 10000$)	Drift 2*	0	68	25	826
			Drift 3	0	4	3	74	

GQAIC	T_n	h_n		Scale 1	Scale 2*	Scale 3	Scale 4	
10	0.01	Drift 1		1	0	0	4	
			($n = 1000$)	Drift 2*	97	591	10	186
			Drift 3	15	86	0	10	
10	0.005	Drift 1		1	0	0	5	
			($n = 2000$)	Drift 2*	99	584	7	191
			Drift 3	15	88	0	10	
50	0.01	Drift 1		0	0	0	0	
			($n = 5000$)	Drift 2*	29	741	36	100
			Drift 3	4	73	5	12	
50	0.005	Drift 1		0	0	0	0	
			($n = 10000$)	Drift 2*	27	747	27	104
			Drift 3	4	74	5	12	

QBIC	T_n	h_n		Scale 1	Scale 2*	Scale 3	Scale 4	
10	0.01	Drift 1		3	0	0	1	
			($n = 1000$)	Drift 2*	142	700	2	36
			Drift 3	14	101	0	1	
10	0.005	Drift 1		3	0	0	2	
			($n = 2000$)	Drift 2*	142	700	1	37
			Drift 3	14	100	0	1	
50	0.01	Drift 1		0	0	0	0	
			($n = 5000$)	Drift 2*	42	890	9	22
			Drift 3	3	33	0	1	
50	0.005	Drift 1		0	0	0	0	
			($n = 10000$)	Drift 2*	38	894	6	23
			Drift 3	3	35	0	1	

GQBIC [#]	T_n	h_n		Scale 1	Scale 2*	Scale 3	Scale 4	
10	0.01	Drift 1		0	0	0	10	
			($n = 1000$)	Drift 2*	15	189	32	685
			Drift 3	2	14	2	51	
10	0.005	Drift 1		0	0	0	10	
			($n = 2000$)	Drift 2*	10	130	35	743
			Drift 3	1	12	2	57	
50	0.01	Drift 1		0	0	0	0	
			($n = 5000$)	Drift 2*	3	200	84	686
			Drift 3	0	4	2	21	
50	0.005	Drift 1		0	0	0	0	
			($n = 10000$)	Drift 2*	1	159	49	763
			Drift 3	0	3	2	23	

Model-selection frequencies in (iii) $\mathcal{L}(Z_t) = NIG\left(\frac{25}{3}, \frac{20}{3}, \frac{9}{5}t, -\frac{12}{5}t\right)$

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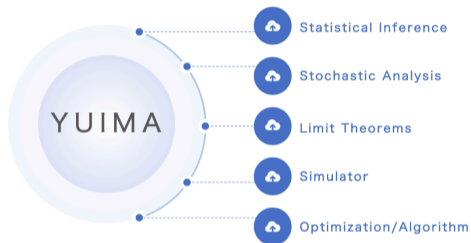
CIC	T_n	h_n		Scale 1	Scale 2*	Scale 3	Scale 4
10 ($n = 1000$)	0.01	Drift 1		0	0	0	0
			Drift 2*	0	128	52	600
			Drift 3	0	30	30	160
10 ($n = 2000$)	0.005	Drift 1		0	0	0	1
			Drift 2*	0	88	37	653
			Drift 3	0	25	16	180
50 ($n = 5000$)	0.01	Drift 1		0	0	0	0
			Drift 2*	0	88	75	731
			Drift 3	0	12	4	9
50 ($n = 10000$)	0.005	Drift 1		0	0	0	0
			Drift 2*	0	70	39	785
			Drift 3	0	6	1	99

GQAIC	T_n	h_n		Scale 1	Scale 2*	Scale 3	Scale 4
10 ($n = 1000$)	0.01	Drift 1		0	0	0	0
			Drift 2*	18	589	33	155
			Drift 3	32	125	33	15
10 ($n = 2000$)	0.005	Drift 1		0	0	0	1
			Drift 2*	15	602	30	149
			Drift 3	32	122	32	17
50 ($n = 5000$)	0.01	Drift 1		0	0	0	0
			Drift 2*	0	672	102	122
			Drift 3	0	80	8	16
50 ($n = 10000$)	0.005	Drift 1		0	0	0	0
			Drift 2*	0	710	77	110
			Drift 3	0	78	4	21

QBIC	T_n	h_n		Scale 1	Scale 2*	Scale 3	Scale 4
10 ($n = 1000$)	0.01	Drift 1		0	0	0	0
			Drift 2*	24	798	5	5
			Drift 3	35	133	0	0
10 ($n = 2000$)	0.005	Drift 1		0	0	0	0
			Drift 2*	25	795	4	4
			Drift 3	37	135	0	0
50 ($n = 5000$)	0.01	Drift 1		0	0	0	0
			Drift 2*	0	943	28	0
			Drift 3	0	28	1	0
50 ($n = 10000$)	0.005	Drift 1		0	0	0	0
			Drift 2*	0	957	16	0
			Drift 3	0	26	1	0

GQBIC [#]	T_n	h_n		Scale 1	Scale 2*	Scale 3	Scale 4
10 ($n = 1000$)	0.01	Drift 1		0	0	0	0
			Drift 2*	0	264	64	477
			Drift 3	5	37	45	108
10 ($n = 2000$)	0.005	Drift 1		0	0	0	1
			Drift 2*	0	181	48	565
			Drift 3	2	35	29	139
50 ($n = 5000$)	0.01	Drift 1		0	0	0	0
			Drift 2*	0	210	136	619
			Drift 3	0	7	1	27
50 ($n = 10000$)	0.005	Drift 1		0	0	0	0
			Drift 2*	0	166	96	708
			Drift 3	0	4	1	25

YUIMA package



ASSESSMENT

- Mean squared error analysis
- Goodness-of-fit testing
- Residual analysis
- Information criteria, ...

ANALYSIS & ASYMPTOTICS

- Parameter estimation
- Quantitative confidence set
- Prediction uncertainty, ...



IDEA

- Sometimes intuitive
- Ideally simple enough and practical

MODEL BUILDING

- Randomly perturbed dynamical system
- Linear and/or non-linear
- Noise character, ...

- Documents: [Brouste et al., 2014], [Iacus and Yoshida, 2018], ...
- Demonstrated also by e.g. *Quant Education*: <https://www.youtube.com/watch?v=trWzgLj20XU>
- <https://r-forge.r-project.org/projects/yuima/>

- 1 Setup and objective
- 2 Estimation: GQMLE
- 3 Selection: GQAIC and GQBIC
- 4 Simulations
- 5 Concluding remarks**

Summary: Noise character does significantly matter

- Inference based on the two-stage Gaussian quasi-likelihood:

True data-generating process \leftarrow Statistical model \mathcal{M}_{m_1, m_2} ($m_1 \leq M_1$, $m_2 \leq M_2$)

$$dX_t = C(X_{t-})dZ_t + A(X_t)dt \leftarrow dX_t = a_{m_2}(X_t, \alpha_{m_2})dt + c_{m_1}(X_{t-}, \gamma_{m_1})dZ_t$$

- Estimation of $\theta_{m_1, m_2} = (\alpha_{m_2}, \gamma_{m_1})$ by GQMLE:

$$E \left[f \left(\sqrt{T_n}(\hat{\theta}_n - \theta_0) \right) \right] \rightarrow \int f(u)\phi(u; 0, V(\theta_0))du, \quad \hat{V}_n^{-1/2}\sqrt{T_n}(\hat{\theta}_n - \theta_0) \xrightarrow{\mathcal{L}} N_p(0, I_p).$$

Select $\mathcal{M}_{\hat{m}_{1,n}, \hat{m}_{2,n}}$ for GQXIC type relative model selection ($\mathbf{X} \leftarrow \mathbf{A}, \mathbf{B}$)

$$\{\hat{m}_{1,n}\} = \underset{m_1}{\operatorname{argmin}} \operatorname{GQXIC}_{1,n}^{(m_1)}, \quad \{\hat{m}_{2,n}\} = \underset{m_2}{\operatorname{argmin}} \operatorname{GQXIC}_{2,n}^{(m_2 | \hat{m}_{1,n})} :$$

$$\operatorname{GQAIC}_{1,n} = -2 \mathbb{H}_{1,n}(\hat{\gamma}_n) + \frac{2}{h} \operatorname{trace} \left(\hat{\Gamma}_{\gamma,n}^{-1} \hat{W}_{\gamma,n} \right), \quad \operatorname{GQAIC}_{2,n} = -2 \mathbb{H}_{2,n}(\hat{\alpha}_n) + 2p_\alpha,$$

$$\operatorname{GQBIC}_{1,n} = -2 \mathbb{H}_{1,n}(\hat{\gamma}_n) + \frac{p_\gamma}{h} \log T_n, \quad \operatorname{GQBIC}_{2,n} = -2 \mathbb{H}_{2,n}(\hat{\alpha}_n) + p_\alpha \log T_n.$$

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Preliminary observations I

- Assume that $0 < \#\mathfrak{M}_1 < M_1$ and $0 < \#\mathfrak{M}_2 < M_2$, where $\#\mathfrak{M}_1$ and $\#\mathfrak{M}_2$ denote the numbers of elements of \mathfrak{M}_1 and \mathfrak{M}_2 , respectively, with

$$\mathfrak{M}_1 := \{m_1 \in \{1, \dots, M_1\} : \text{there exists a } \gamma_{m_1,0} \in \Theta_{\gamma_{m_1}} \text{ such that } c_{m_1}(\cdot, \gamma_{m_1,0}) = C(\cdot)\},$$

$$\mathfrak{M}_2 := \{m_2 \in \{1, \dots, M_2\} : \text{there exists a } \alpha_{m_2,0} \in \Theta_{\alpha_{m_2}} \text{ such that } a_{m_2}(\cdot, \alpha_{m_2,0}) = A(\cdot)\}.$$

- The candidate coefficients c_1, \dots, c_{M_1} and a_1, \dots, a_{M_2} contain both correctly specified coefficients and misspecified coefficients.
- See [Uehara, 2019] for asymptotics for misspecified-coefficient case.

Preliminary observations II

- Using the GQAIC, the stepwise model comparison is performed as follows.
 - We compute $\text{GQAIC}_{1,n}$ for each candidate scale coefficient, say $\text{GQAIC}_{1,n}^{(1)}, \dots, \text{GQAIC}_{1,n}^{(M_1)}$, and select the best scale coefficient $c_{\hat{m}_{1,n}}$ having the minimum $\text{GQAIC}_{1,n}$ -value:

$$\{\hat{m}_{1,n}\} = \underset{1 \leq m_1 \leq M_1}{\operatorname{argmin}} \text{GQAIC}_{1,n}^{(m_1)}.$$

- Under the result of (i), we choose the best drift coefficient with index $\hat{m}_{2,n}$ such that

$$\{\hat{m}_{2,n}\} = \underset{1 \leq m_2 \leq M_2}{\operatorname{argmin}} \text{GQAIC}_{2,n}^{(m_2|\hat{m}_{1,n})},$$

where $\text{GQAIC}_{2,n}^{(m_2|m_{1,n})}$ corresponds to (3.6) with $c_{m_{1,n}}$ and $\hat{\gamma}_{m_{1,n},n}$.

- The total number of comparisons in this procedure is $M_1 + M_2$, and we can obtain the model $\mathcal{M}_{\hat{m}_{1,n}, \hat{m}_{2,n}}$ as the final best model among the candidates.
- When we use GQBIC for model comparison, the best model is selected by a similar procedure.

Preliminary observations III

- Let the functions $\mathbb{H}_{1,n}^{(m_1)}$ and $\mathbb{H}_{2,n}^{(m_2|m_1)}$ denote $\mathbb{H}_{1,n}$ and $\mathbb{H}_{2,n}$ in each candidate model \mathcal{M}_{m_1, m_2} , respectively. Then, we have

$$\frac{1}{n} \mathbb{H}_{1,n}^{(m_1)}(\gamma_{m_1}) \xrightarrow{P} -\frac{1}{2} \int_{\mathbb{R}^d} \left\{ \text{trace} (S(x, \gamma_{m_1})^{-1} S(x)) + \log |S(x, \gamma_{m_1})| \right\} \pi(dx) =: \mathbb{H}_{1,0}^{(m_1)}(\gamma_{m_1}),$$

where $S(x) = C(x)^{\otimes 2}$. We assume that the optimal scale parameter $\gamma_{m_1}^*$ and scale index set \mathfrak{M}_1^* are respectively defined as

$$\{\gamma_{m_1}^*\} = \operatorname{argmax}_{\gamma_{m_1}} \mathbb{H}_{1,0}^{(m_1)}(\gamma_{m_1}), \quad \mathfrak{M}_1^* = \operatorname{argmin}_{m_1 \in \mathfrak{M}_1} \dim(\Theta_{\gamma_{m_1}}).$$

- For any $m_1 \in \mathfrak{M}_1$, $\gamma_{m_1}^* = \gamma_{m_1,0}$.

Preliminary observations IV

- Next, for any fixed $m_1 \in \{1, \dots, M_1\}$,

$$\frac{1}{T_n} \mathbb{H}_{2,n}^{(m_2|m_1)}(\alpha_{m_2}) \xrightarrow{P} -\frac{1}{2} \int_{\mathbb{R}^d} S^{-1}(x, \gamma_{m_1}^*) \left[(a_{m_2}(x, \alpha_{m_2}) - A(x))^{\otimes 2} \right] \pi(dx) =: \mathbb{H}_{2,0}^{(m_2|m_1)}(\alpha_{m_2}),$$

and assume that the optimal drift parameter $\alpha_{m_2}^*$ is given by maximizing $\mathbb{H}_{2,0}^{(m_2|m_1)}$:

$$\{\alpha_{m_2}^*\} = \operatorname{argmax}_{\alpha_{m_2}} \mathbb{H}_{2,0}^{(m_2|m_1)}(\alpha_{m_2}).$$

- When m_2 is included in \mathfrak{M}_2 , $\alpha_{m_2}^* = \alpha_{m_2,0}$.
- We also suppose that the drift index set \mathfrak{M}_2^* is defined as

$$\mathfrak{M}_2^* = \operatorname{argmin}_{m_2 \in \mathfrak{M}_2} \dim(\Theta_{\alpha_{m_2}}).$$

- From the assumptions and definitions of $\mathbb{H}_{1,0}^{(m_1)}$ and $\mathbb{H}_{2,0}^{(m_2|m_1)}$, $\mathfrak{M}_1 = \operatorname{argmax}_{m_1} \mathbb{H}_{1,0}^{(m_1)}(\gamma_{m_1}^*)$ and $\mathfrak{M}_2 = \operatorname{argmax}_{m_2} \mathbb{H}_{2,0}^{(m_2|m_1)}(\alpha_{m_2}^*)$ hold.

Preliminary observations V

- Let $\Theta_{\gamma_{i_1}} \times \Theta_{\alpha_{i_2}} \subset \mathbb{R}^{p_{\gamma_{i_1}}} \times \mathbb{R}^{p_{\alpha_{i_2}}}$ and $\Theta_{\gamma_{j_1}} \times \Theta_{\alpha_{j_2}} \subset \mathbb{R}^{p_{\gamma_{j_1}}} \times \mathbb{R}^{p_{\alpha_{j_2}}}$ be the parameter space associated with model \mathcal{M}_{i_1, i_2} and \mathcal{M}_{j_1, j_2} , respectively.
- If $p_{\gamma_{i_1}} < p_{\gamma_{j_1}}$ and there exists a matrix $F_1 \in \mathbb{R}^{p_{\gamma_{j_1}} \times p_{\gamma_{i_1}}}$ with $F_1^\top F_1 = I_{p_{\gamma_{i_1}} \times p_{\gamma_{i_1}}}$ as well as a $\mathbb{H}_{1,n}^{(i_1)}(\gamma_{i_1}) = \mathbb{H}_{1,n}^{(j_1)}(F_1 \gamma_{i_1} + c_1)$ for all $\gamma_{i_1} \in \Theta_{\gamma_{i_1}}$, we say $\Theta_{\gamma_{i_1}}$ is **nested** in $\Theta_{\gamma_{j_1}}$.
- It is defined in a similar manner that $\Theta_{\alpha_{i_2}}$ is nested in $\Theta_{\alpha_{j_2}}$.
- Let $\text{GQBIC}_{1,n}^{(m_1)}$ and $\text{GQBIC}_{1,n}^{\sharp(m_1)}$ denote the $\text{GQBIC}_{1,n}$ and $\text{GQBIC}_{1,n}^{\sharp}$ of the m_1 -th candidate scale coefficient, respectively. Also, let $\text{GQBIC}_{2,n}^{(m_2|m_{1,n})}$ correspond to (3.10) associated with $c_{m_1,n}$ and $\hat{\gamma}_{m_1,n,n}$.

GQAIC is asymptotically weighed chi-square distributed

- Somewhat complicated description: [Eguchi and Masuda, 2024, Theorem 5]
- Summary
 - The probability of relative selection is asymptotically characterized by the non-central chi-squared distribution; in general, this happens when an estimator under consideration is asymptotically normally distributed with the asymptotic covariance matrix being of the sandwich form (see [Kent, 1982]).
 - Further, the probability that GQAIC chooses the misspecified coefficients tends to 0 as $n \rightarrow \infty$.

GQBIC has selection consistency I

Theorem 6.1

Suppose that the assumptions of Theorem 3.1 hold for all candidate coefficients which are included in \mathfrak{M}_1 . We also assume that index m_1^* satisfies $m_1^* \in \mathfrak{M}_1^*$.

① Let $m_1 \in \mathfrak{M}_1 \setminus \{m_1^*\}$. If $\Theta_{\gamma_{m_1^*}}$ is nested in $\Theta_{\gamma_{m_1}}$, then

$$\lim_{n \rightarrow \infty} P \left(\text{GQBIC}_{1,n}^{\sharp(m_1^*)} > \text{GQBIC}_{1,n}^{\sharp(m_1)} \right) = 1.$$

② If $m_1 \in \{1, \dots, M_1\} \setminus \mathfrak{M}_1$, then

$$\lim_{n \rightarrow \infty} P \left(\text{GQBIC}_{1,n}^{\sharp(m_1^*)} < \text{GQBIC}_{1,n}^{\sharp(m_1)} \right) = 1.$$

GQBIC has selection consistency II

Theorem 6.2

Suppose that the assumptions of Theorem 3.1 hold for all candidate coefficients which are included in \mathfrak{M}_1 and \mathfrak{M}_2 . We also assume that indexes m_1^* and m_2^* satisfy $m_1^* \in \mathfrak{M}_1^*$ and $m_2^* \in \mathfrak{M}_2^*$, respectively.

- ① If $\Theta_{\gamma_{m_1^*}}$ is nested in $\Theta_{\gamma_{m_1}}$ for $m_1 \in \mathfrak{M}_1 \setminus \{m_1^*\}$, or if $m_1 \in \{1, \dots, M_1\} \setminus \mathfrak{M}_1$, then

$$\lim_{n \rightarrow \infty} P \left(\text{GQBIC}_{1,n}^{(m_1^*)} < \text{GQBIC}_{1,n}^{(m_1)} \right) = 1.$$

- ② If $\Theta_{\alpha_{m_2^*}}$ is nested in $\Theta_{\alpha_{m_2}}$ for $m_2 \in \mathfrak{M}_2 \setminus \{m_2^*\}$, or if $m_2 \in \{1, \dots, M_2\} \setminus \mathfrak{M}_2$, then

$$\lim_{n \rightarrow \infty} P \left(\text{GQBIC}_{2,n}^{(m_2^* | \hat{m}_{1,n})} < \text{GQBIC}_{2,n}^{(m_2 | \hat{m}_{1,n})} \right) = 1.$$

- Theorem 6.1.1 shows that, when comparing correctly specified models, the probability that $\text{GQBIC}_{1,n}^\#$ selects a larger model tends to 1. Moreover, Theorem 6.2 means that the GQBIC proposed by (3.9) and (3.10) has the model selection consistency.