

Inference for extremal regression with dependent heavy-tailed data

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Motivating example: Tornado loss data

The data (NOAA Storm Prediction Center) contains, for each tornado in the eastern US between 1 January 2010 and 31 December 2019:

- The associated monetary loss,
- Starting and ending latitude and longitude,
- Length and width of the area traveled over.

We consider the **loss per surface** unit $Y = \text{loss}/(\text{length} \times \text{width})$, with covariate $\mathbf{X} \in \mathbb{R}^2$ being the average latitude and longitude of a tornado.

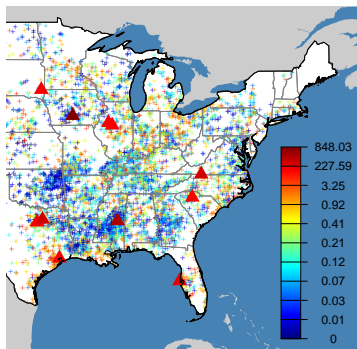
This results in a sample (\mathbf{X}_t, Y_t) of size $n \approx 6,000$, including the 2011 Joplin, Missouri, tornado which caused a total loss of 2.8 billion USD.

Motivating question

What are the financial consequences of a high-impact tornado as a function of the geographical area it hits?

Tornado loss data - Exploratory analysis

(a) Losses per squared-yard



(b) Tornado frequency

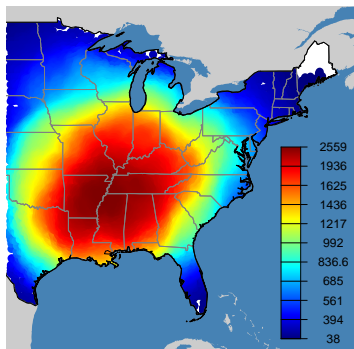
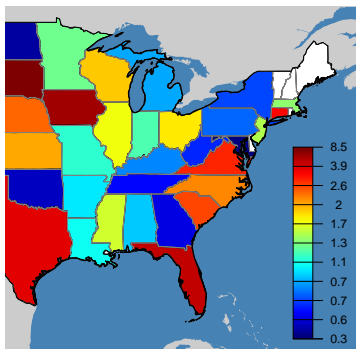


Figure: Tornado loss data. Left: Data across the eastern half of the US, right: Local number of observations.

Tornado loss data - State-by-state analysis

(e) Mean by state



(f) Tail risk (quantile) by state

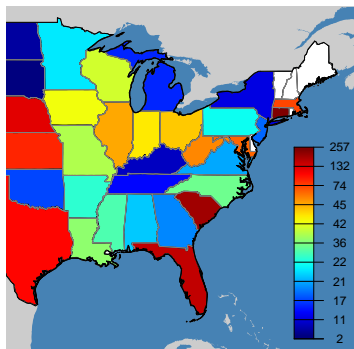


Figure: Tornado loss data. Left: Unconditional statewide estimation, using the sample average, right: Using the bias-reduced extreme quantile estimator of Gomes and Pestana (2007) at level 0.995.

Such region-by-region maps seem to be standard in insurance.

One major issue is that they are inherently **non-smooth** geographically: there are, among others, sharp jumps along the borders of

- The states in the Midwest,
- The states in New England,
- Florida-Georgia-South Carolina.

Inference, in the form of confidence intervals, is not obvious in this setting where data are **dependent in time and nonstationary in space**.

Context of the talk: conditional risk assessment

The (risk) variable Y is recorded alongside a **random** covariate $\mathbf{X} \in \mathbb{R}^p$:

- Y = individual stock price, \mathbf{X} = stock market index $\in \mathbb{R}$,
- Y = loss variable following a climate event, \mathbf{X} = latitude and longitude $\in \mathbb{R}^2$.

No assumption is made on the link between Y and \mathbf{X} , and we seek estimators of extreme **quantiles** and/or **expectiles** of Y given \mathbf{X} .

⇒ The estimation approach has to be **nonparametric**.

Difficulty: Quantiles and expectiles are not expectations. Otherwise, one would immediately think about nonparametric regression!

Two key (known) observations provide the basis for this work.

- The **expectile** of Y is in fact a **quantile**, of the c.d.f. E defined as

$$E(y) = 1 - \frac{\mathbb{E}((Y - y)\mathbb{1}\{Y > y\})}{2\mathbb{E}((Y - y)\mathbb{1}\{Y > y\}) + y - \mathbb{E}(Y)}.$$

This function E is readily estimated.

- If q is the quantile function related to F then $q_\tau \leq t \Leftrightarrow \tau \leq F(t)$.

Both expectile and quantile estimation fall under the umbrella of quantile estimation (first point)...

... and therefore under the umbrella of **c.d.f. estimation** (second point).

Indeed, if \hat{F}_n estimates F and \hat{q}_n is the left-continuous inverse of \hat{F}_n ,

$$\mathbb{P}(\hat{q}_{n,\tau} \leq t) = \mathbb{P}(\tau \leq \hat{F}_n(t)).$$

Position within the literature and contribution

Existing approaches to extreme conditional quantile and expectile estimation use **kernel regression** to estimate $F(\cdot|\mathbf{x})$ and $E(\cdot|\mathbf{x})$.

They assume **i.i.d. data** and do not discuss inference.

Main contribution of the paper

Study the estimation of, and Gaussian inference about, extreme conditional quantiles and expectiles for stationary α -mixing data.

We do so in a conditional **heavy (right) tail** model.

Goal of the presentation

Give a flavor of the theory that can be obtained and briefly discuss a few data-generating processes that can be handled.

Estimation procedure - Intermediate levels

We concentrate on extreme quantile estimation.

Let (\mathbf{X}_t, Y_t) , $t \geq 1$, be **strictly stationary**, and assume that \mathbf{X} has p.d.f. g . The conditional c.d.f. $F(y|\mathbf{x})$ of Y given $\mathbf{X} = \mathbf{x}$ is estimated by

$$\hat{F}_n(y|\mathbf{x}) = \frac{1}{nh_n^p \hat{g}_n(\mathbf{x})} \sum_{t=1}^n \mathbb{1}_{\{Y_t \leq y\}} K\left(\frac{\mathbf{x} - \mathbf{X}_t}{h_n}\right)$$

$$\text{with } \hat{g}_n(\mathbf{x}) = \frac{1}{nh_n^p} \sum_{t=1}^n K\left(\frac{\mathbf{x} - \mathbf{X}_t}{h_n}\right).$$

Here K is a kernel p.d.f. on \mathbb{R}^p and $h_n \rightarrow 0$. Set

$$\hat{q}_n(\tau|\mathbf{x}) = \inf \left\{ y \in \mathbb{R} \mid \hat{F}_n(y|\mathbf{x}) \geq \tau \right\}.$$

This estimator was considered in e.g. Daouia *et al.* (2011, 2013). We first show that it is asymptotically normal at **intermediate** levels.

Model and assumptions

Condition $\mathcal{C}_2(\gamma(\mathbf{x}), \rho(\mathbf{x}), A(\cdot|\mathbf{x}))$ - Conditional heavy tails

There exist $\gamma(\mathbf{x}) > 0$, $\rho(\mathbf{x}) \leq 0$ and a positive or negative measurable function $A(\cdot|\mathbf{x})$ converging to 0 at infinity such that for any $y > 0$,

$$\lim_{s \rightarrow \infty} \frac{\bar{F}(sy|\mathbf{x})/\bar{F}(s|\mathbf{x}) - y^{-1/\gamma(\mathbf{x})}}{A(1/\bar{F}(s|\mathbf{x})|\mathbf{x})} = \frac{y^{-1/\gamma(\mathbf{x})}}{\gamma^2(\mathbf{x})} \int_1^y u^{\rho(\mathbf{x})/\gamma(\mathbf{x})-1} du$$

Condition \mathcal{M} - Time dynamics

The data (\mathbf{X}_t, Y_t) , $t \geq 1$, form a stationary α -mixing sequence of copies of (\mathbf{X}, Y) satisfying assumption $\mathcal{C}_2(\gamma(\mathbf{x}), \rho(\mathbf{x}), A(\cdot|\mathbf{x}))$.

Recall that (\mathbf{X}_t, Y_t) is α -mixing if, with $\mathcal{F}_a^b = \sigma(\{(\mathbf{X}_j, Y_j), a \leq j \leq b\})$,

$$\alpha(n) = \sup_{k \geq 1} \sup_{A \in \mathcal{F}_1^k} \sup_{B \in \mathcal{F}_{k+n}^\infty} |\mathbb{P}(A \cap B) - \mathbb{P}(A)\mathbb{P}(B)| \rightarrow 0 \text{ as } n \rightarrow \infty.$$

Condition $\mathcal{A}(l_n, r_n)$ - Big-block/small-block

There exist sequences (l_n) and (r_n) such that $l_n \rightarrow \infty$, $r_n \rightarrow \infty$, $l_n/r_n \rightarrow 0$, $r_n/n \rightarrow 0$ and $n\alpha(l_n)/r_n \rightarrow 0$ as $n \rightarrow \infty$.

This ensures **asymptotic independence** of “big blocks” separated by “small blocks” of sample means.

We require regularity conditions on \mathbf{X} and $Y|\mathbf{X}$. Fix a norm $\|\cdot\|$ on \mathbb{R}^p .

Condition \mathcal{KS} - Kernel

K is bounded and symmetric (i.e. $K(\mathbf{u}) = K(-\mathbf{u})$) with a support contained in the unit closed $\|\cdot\|$ -ball.

Condition \mathcal{D}_g - Regularity

$g(\mathbf{x}) > 0$ and g is continuously differentiable in a neighborhood of \mathbf{x} with a Lipschitz continuous gradient at \mathbf{x} .

Condition \mathcal{D}_ω - Variation in conditional extreme value behavior

For y large enough, the function $\bar{F}(y|\cdot)$ is differentiable at \mathbf{x} , the function $y \mapsto \nabla_{\mathbf{x}} \log \bar{F}(y|\mathbf{x}) / \log(y)$ has a limit $\boldsymbol{\mu}(\mathbf{x}) \in \mathbb{R}^p$ as $y \rightarrow \infty$, and there exists $r > 0$ such that

$$\frac{1}{\|\mathbf{x}' - \mathbf{x}\|^2} \left| \frac{1}{\log(y)} \log \frac{\bar{F}(y|\mathbf{x}')}{\bar{F}(y|\mathbf{x})} - (\mathbf{x}' - \mathbf{x})^\top \frac{\nabla_{\mathbf{x}} \log \bar{F}(y|\mathbf{x})}{\log(y)} \right| < \infty$$

is uniformly bounded for $\mathbf{x}' \in B(\mathbf{x}, r)$ and y large.

Conditions \mathcal{KS} , \mathcal{D}_g and \mathcal{D}_ω amount to (being able to use the) **twice differentiability** of the distribution of \mathbf{X} and of the extreme value behavior of Y given \mathbf{X} .

We finally make two anti-clustering assumptions, one on \mathbf{X} and the other on \mathbf{Y} given \mathbf{X} .

Condition \mathcal{B}_p - Anti-clustering in small balls

There exists an integer $t_0 \geq 1$ such that

$$1 \leq t < t_0 \Rightarrow \lim_{r \rightarrow 0} r^{-p} \mathbb{P}(\mathbf{X}_1 \in B(\mathbf{x}, r), \mathbf{X}_{t+1} \in B(\mathbf{x}, r)) = 0$$

$$\text{and } \limsup_{r \rightarrow 0} \sup_{t \geq t_0} r^{-2p} \mathbb{P}(\mathbf{X}_1 \in B(\mathbf{x}, r), \mathbf{X}_{t+1} \in B(\mathbf{x}, r)) < \infty.$$

Condition \mathcal{B}_p means that values of (\mathbf{X}_t) close in time might concentrate somewhat around \mathbf{x} but those far apart in time cannot.

Under \mathcal{D}_g , \mathcal{B}_p is automatically true if (\mathbf{X}_t) is β -mixing, because then $(\mathbf{X}_1, \mathbf{X}_{t+1})$ has a p.d.f. g_t uniformly bounded in t around (\mathbf{x}, \mathbf{x}) .

When $p \geq 2$, the causal and invertible AR(p) process does not satisfy this boundedness condition, but satisfies assumption \mathcal{B}_p with $t_0 = p$.

Condition \mathcal{B}_Ω - Anti-clustering on conditional extremes

There exist $h, z > 0$ such that $\Omega_h(z|\mathbf{x}) < \infty$, where

$$\Omega_h(z|\mathbf{x}) = \sup_{t \geq 1} \sup_{\substack{\mathbf{x}', \mathbf{x}'' \in B(\mathbf{x}, h) \\ y, y' \geq z}} \frac{\mathbb{P}(Y_1 > y, Y_{t+1} > y' | \mathbf{X}_1 = \mathbf{x}', \mathbf{X}_{t+1} = \mathbf{x}'')}{\sqrt{\bar{F}(y|\mathbf{x}')\bar{F}(y'|\mathbf{x}'')}}.$$

Condition \mathcal{B}_Ω means that a **joint conditional extreme value** of (Y_1, Y_{t+1}) cannot be much more likely than a marginal conditional extreme of Y_1 , uniformly across time and locally uniformly across the covariate space.

It is (interestingly) **much weaker** in spirit than analogue conditions in the unconditional setting.

Theorem (Intermediate quantiles - A.D., G.S. and A.U.-C. AoS 2023)

Assume that $\sum_{j=1}^{\infty} j^{\eta} \alpha(j) < \infty$ for some $\eta > 1$. Let $\tau_n \uparrow 1$ and $h_n \rightarrow 0$ be such that $nh_n^p(1 - \tau_n) \rightarrow \infty$ and $r_n h_n^p \rightarrow 0$, and suppose

- $nh_n^p(1 - \tau_n)\{h_n \log(1 - \tau_n)\}^4 \rightarrow 0$,
- $\sqrt{nh_n^p(1 - \tau_n)}A((1 - \tau_n)^{-1}|\mathbf{x}) = O(1)$,
- There is $\delta > 0$ such that $r_n(r_n/\sqrt{nh_n^p(1 - \tau_n)})^{\delta} \rightarrow 0$.

Then

$$\sqrt{nh_n^p(1 - \tau_n)} \left(\frac{\hat{q}_n(\tau_n|\mathbf{x})}{q(\tau_n|\mathbf{x})} - 1 \right) \xrightarrow{d} \mathcal{N} \left(0, \frac{\int_{\mathbb{R}^p} K^2}{g(\mathbf{x})} \gamma^2(\mathbf{x}) \right).$$

Certain conditions can be dropped if the data-generating process satisfies stronger mixing conditions (relevant for examples!)

A stronger, joint convergence result for **several** intermediate quantile estimators is available and shall prove useful for the estimation of $\gamma(\mathbf{x})$.

Remarks

The asymptotic distribution with dependent (\mathbf{X}_t, Y_t) is the same as in the i.i.d. setting (see Daouia *et al.*, 2011). This is specific to **nonparametric regression** problems (see e.g. Linton and Xiao, 2013).

The optimal (over τ_n and h_n) rate of convergence is $n^{2\rho(\mathbf{x})/(2-(p+4)\rho(\mathbf{x}))}$, for intermediate conditional quantiles with $\tau_n = 1 - Cn^{-2/(2-(p+4)\rho(\mathbf{x}))}$.

When $\rho(\mathbf{x}) \rightarrow -\infty$, corresponding to the pure conditional Pareto model, the optimal convergence rate is $n^{-2/(p+4)}$ (for central quantiles).

This is the optimal convergence rate $n^{-2/(p+4)}$ for **central** conditional quantiles under twice differentiability. (Improvement w.r.t. literature!)

Estimation procedure - Extreme levels

At properly extreme levels, $\hat{q}_n(\tau_n|\mathbf{x})$ is not consistent. But

$$q(\tau'|\mathbf{x}) \approx \left(\frac{1 - \tau'}{1 - \tau} \right)^{-\gamma(\mathbf{x})} q(\tau|\mathbf{x}) \text{ when } \tau, \tau' \uparrow 1.$$

Plugging in a consistent estimator $\hat{\gamma}(\mathbf{x})$ of $\gamma(\mathbf{x})$ yields a conditional Weissman-type estimator of $q(\tau'_n|\mathbf{x})$ when τ'_n is extreme:

$$\hat{q}_{n,\tau_n}^W(\tau'_n|\mathbf{x}) = \left(\frac{1 - \tau'_n}{1 - \tau_n} \right)^{-\hat{\gamma}(\mathbf{x})} \hat{q}_n(\tau_n|\mathbf{x}), \text{ where } \frac{1 - \tau'_n}{1 - \tau_n} \rightarrow 0.$$

We use a (somewhat) **Hill-type estimator** from Daouia *et al.* (2011):

$$\hat{\gamma}_{\tau_n}^{(J)}(\mathbf{x}) = \frac{1}{\log(J!)} \sum_{j=1}^J \log \left(\frac{\hat{q}_n(1 - (1 - \tau_n)/j|\mathbf{x})}{\hat{q}_n(\tau_n|\mathbf{x})} \right), \text{ for a fixed } J \geq 2.$$

Theorem (Extreme quantiles - A.D., G.S. and A.U.-C. AoS 2023)

Assume also that $\rho(\mathbf{x}) < 0$ and $\sqrt{nh_n^p(1-\tau_n)}A((1-\tau_n)^{-1}|\mathbf{x}) \rightarrow 0$.
 Let $\tau'_n \uparrow 1$ be such that $\sqrt{nh_n^p(1-\tau_n)}/\log[(1-\tau_n)/(1-\tau'_n)] \rightarrow \infty$.
 Then

$$\frac{\sqrt{nh_n^p(1-\tau_n)}}{\log[(1-\tau_n)/(1-\tau'_n)]} \left(\frac{\widehat{q}_{n,\tau_n}^W(\tau'_n|\mathbf{x})}{q(\tau'_n|\mathbf{x})} - 1 \right) \xrightarrow{d} \mathcal{N} \left(0, \frac{\int_{\mathbb{R}^p} K^2}{g(\mathbf{x})} \gamma^2(\mathbf{x}) \frac{J(J-1)(2J-1)}{6 \log^2(J!)} \right).$$

This relies on the asymptotic normality of $\widehat{\gamma}_{\tau_n}^{(J)}(\mathbf{x})$, which uses the joint asymptotic normality of J intermediate conditional smoothed quantiles.

Some models where our assumptions are satisfied

Our conditions hold in:

- **Location-scale** models $Y_t = m(\mathbf{X}_t) + \sigma(\mathbf{X}_t)\varepsilon_t$ where m and $\sigma > 0$, and (ε_t) is a stationary and centered sequence of unobserved heavy-tailed innovations independent from the sequence (\mathbf{X}_t) .
- **Nonlinear** regression models $Y_t = q(U_t, \theta(\mathbf{X}_t))$ where (U_t) is a stationary sequence of unobserved, uniformly distributed innovations independent from the sequence (\mathbf{X}_t) , and $q(\cdot, \theta)$ is a smooth parametric family of heavy-tailed quantile functions.
- **Autoregressive** models with heavy-tailed innovations, with the covariate made of lags of the response.

Regularity conditions (e.g. on $m, \sigma, \theta \dots$) are of course necessary!

Back to the tornado loss data analysis

It was checked using **local Generalized Pareto QQ-plots** that the response Y is heavy-tailed conditional on X .

We represent (a **bias-corrected** version of) $\hat{q}_{n,\tau_n}^W(0.995|x)$ at each location x , along with the Nadaraya-Watson estimator.

The extreme quantile estimate is calculated using data-driven selection rules of τ_n and h_n geared towards **MSE minimization**.

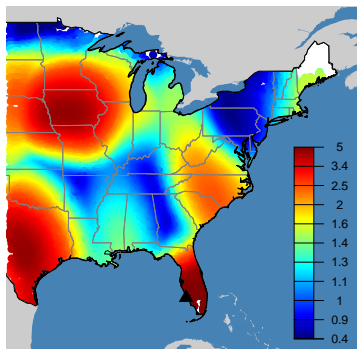
We also provide **pointwise** asymptotic Gaussian **95%** confidence intervals, with a couple of corrections to try to improve coverage.

Two questions:

- Are the regression and extreme value analyses different?
- Is kernel smoothing able to smooth over the state-by-state analysis?

Tornado loss data - Regression analysis

(c) Regression mean



(d) Regression tail risk (quantile)

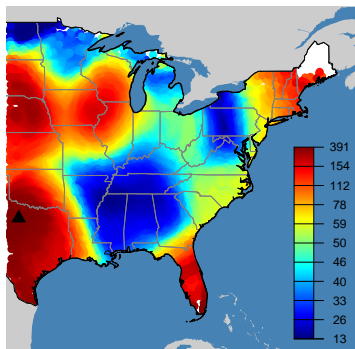


Figure: Tornado loss data. Left: Estimated conditional mean of losses per squared yard, right: Extrapolated conditional quantile estimate of those losses at level $\tau'_n = 0.995$. Cities with the highest estimated conditional average loss and extreme loss are marked with a black triangle in the left and right panels.

Location \mathbf{x}	$N_{h_{n,*}}(\mathbf{x})$	$\hat{\gamma}_{1-k_{n,*}/n}^{(J, BR)}(\mathbf{x})$	$\hat{q}_n(0.995 \mathbf{x})$	$\hat{q}_{n,1-k_{n,*}/n}^{W, BR}(0.995 \mathbf{x})$
New York (NY)	413	1.11	16.71 [2.46, 113.35]	63.53 [18.13, 222.70]
Charleston (SC)	839	0.96	48.08 [12.54, 184.28]	56.15 [22.58, 139.64]
Nashville (TN)	2,317	0.95	16.57 [8.31, 33.04]	24.51 [14.62, 41.08]
Captiva (FL)	205	0.93	236.74 [36.08, 1553.36]	144.67 [43.50, 481.13]
New Orleans (LA)	1,427	0.98	27.46 [11.44, 65.88]	31.01 [16.42, 58.58]
Woodson (TX)	958	1.53	118.37 [16.53, 847.72]	390.59 [100.95, 1511.26]
Kansas City (MO)	1,326	1.30	45.99 [11.29, 187.43]	69.00 [25.57, 186.21]
Minneapolis (MN)	620	0.93	34.09 [9.54, 121.79]	40.49 [17.01, 96.40]
Harrisville (MI)	472	0.79	24.86 [4.76, 129.71]	29.32 [10.28, 83.67]

Table: Tornado loss data. Results at selected cities, with the number of neighboring observations, along with 95% asymptotic confidence intervals. Captiva, FL is the city with maximal estimated average loss.

Conclusion

We revisit **nonparametric extremal regression** estimation via kernel smoothing for the conditional distribution function.

We find optimal rates akin to those of central **nonparametric regression**, under appropriate twice differentiability conditions w.r.t. \mathbf{x} .

Our assumptions hold for a variety of regression models and time series.

I did not talk about: Particular challenges of expectile regression (bias/variance correction), tuning parameter selection, simulation results for $\mathbf{X} \in \mathbb{R}$ or \mathbb{R}^2 , a stock market data analysis...

For more, see Daouia, S. & Usseglio-Carleve (2023). Inference for extremal regression with dependent heavy-tailed data, *Annals of Statistics* **51**(5): 2040-2066.

Thank you for your attention!